

CG: A COMBINATORIAL GEOMETRY MODULE
FOR THE MICOM LASER TERMINAL
HOMING SYSTEMS PROGRAM

Final Report

July 1973

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for

U. S. Army Missile Command
Huntsville, Alabama

MICOM Contract No. DAAH01-73-C-0761

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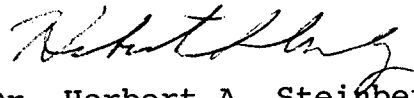
July 18, 1974
M-4431

Dr. Ely M. Gelbard
Applied Physics Division
Building 208
Argonne National Laboratory
9700 South Cass Avenue
Argonne, Illinois 60439

Dear Dr. Gelbard:

Enclosed is a report describing the MAGI Combinatorial Geometry System. Some improvements and corrections have been made since this report was written, the most significant being the Checker described by Marty Cohen at the June 1974 ANS Meeting. The latest version (without listings) is described in the SAM-CE (Rev. C) Manual which will be released shortly. If you are interested in SAM-CE itself, notify Dr. Cohen or myself and we will send you a copy when it is published. The code (SAM-CE or the geometry package) will be distributed through RSIC.

Very truly yours,



Dr. Herbert A. Steinberg
Director, Scientific Services

HAS/br
Enc.

ABSTRACT

CG is the designation for a code module, which utilizes Combinatorial Geometry techniques to provide efficient modeling of complex three-dimensional targets. Its modular structure alleviates implementation in a parent program, such as the MICOM LTHS program. Interfacing with the parent code is limited to one "input" and one "output" labeled common block. Given a source ray and detector position, the CG module represents a versatile means of accounting for the purely geometric effects of a target, such as the T-54 tank.

ACKNOWLEDGEMENTS

Mr. Walter Guber is primarily responsible for the Combinatorial Geometry techniques. The T-54 tank model is a modification of the original description by Mr. Robert Goldstein.

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1. INTRODUCTION

1.1 Program Objective

CG is a FORTRAN code module comprising an executive routine (SUBROUTINE CGPACK), and eight subordinate routines, which comprise the standard MAGI Combinatorial Geometry (CG) package^{1,2}. This module was designed for implementation in the MICOM LTHS program, with minimal code interfacing, to provide efficient ray tracing for complex target geometries.

1.2 Scope of Report

This report is designed to be used as an operational manual, and to serve as a descriptive summary of the Combinatorial Geometry technique in general, and the CG code module in particular. Consequently, the main body includes sections describing: (a) the CG technique; (b) preparation of CG input; and (c) the routines comprising the CG module. In addition, listings of the CG module and the CG description of a T-54 tank model are included in the appendices.

2. THE CG TECHNIQUE FOR THE DESCRIPTION AND COMPUTER PROCESSING OF COMPLEX THREE-DIMENSIONAL OBJECTS

2.1 Introduction

Combinatorial Geometry (CG) is essentially a technique for representing, in a computer, a mathematical model of a three-dimensional geometric configuration. Once in the computer, the configuration can be analyzed in many different ways by ray tracing techniques. For example, quantities such as volumes, surface areas, object boundaries, line of sight distances, etc. are readily determined. Regardless of the application, however, the basic concepts employed are the same. A discussion of these concepts can logically be broken down into two topics. That is, geometry description and ray tracing, which are discussed separately below.

2.2 Description of the Combinatorial Geometry Technique

In order to perform computer studies concerning a complex three-dimensional object one must first be able to prepare a mathematical model of the object, and its environment. The CG technique has been developed to permit a model to be produced, which is both accurate and suitable for a ray-tracing analysis program.

In effect the geometric description subdivides the problem space into unique regions. This is achieved through the use of ten specific geometric bodies (closed surfaces) and the orderly identification of the combination of those bodies, which define a region (space volume). The bodies, which will be discussed further in PREPARATION OF CG INPUT (Sec. 3), are as follows:

1. Rectangular Parallelepiped (RPP)
2. Box
3. Sphere
4. Right Circular Cylinder
5. Right Elliptical Cylinder
6. Truncated Right Angle Cone
7. Ellipsoid of Revolution
8. Right Angle Wedge
9. Arbitrary Convex Polyhedron of four, five or six sides (each side having three or four vertices).
10. Truncated Elliptic Cone

Except for the RPP's, all bodies may be arbitrarily oriented with respect to the x, y, z coordinate axes used to determine the space. It should be noted that the sides of an RPP must be parallel to the coordinate axes.

2.2.1 Region Description Technique

The basic technique for the description of the geometry consists of defining the location and shape of the various physical regions (wall, equipment, etc.) in terms of the intersections and unions of the volumes contained in a set of simple bodies. A special operator notation involving the symbols (+), (-), and (OR) is used to describe the intersections and unions. These symbols are used by the program to construct tables used in the ray-tracing portion of the problem.

If a body appears in a region description with a (+) operator, it means that the region being described is wholly contained in the body.

If a body appears in a region description with a (-) operator, it means that the region being described is wholly outside the body.

The (OR) operator is used to form regions as unions of subregions, where each subregion is defined in terms of one or more bodies, using (+) or (-) as described above. Then a point is in the region if it is in any subregion.

The technique of describing a physical region is best illustrated by an example. Consider an object composed of a sphere into which is inserted a cylinder. This is shown in cross section in Fig. 1(a).

To describe the object, we take a spherical body penetrated by a cylindrical body {Fig.1(b)}. Each body is numbered. Consider the sphere as body No. 1 and cylinder as body No. 2. If the materials in the sphere and cylinder are the same, then they can be considered as one physical region, say region 100 {Fig. 1(c)}.

The description of region 100 would be:

$$100 = (\text{OR } 1) (\text{OR } 2).$$

This means that a point is in region 100 if it is either inside body 1 or inside body 2.

If different materials are used in the sphere and cylinder, then the sphere with a cylindrical hole in it would be given a different region number (say 200) from that of the cylinder (300).

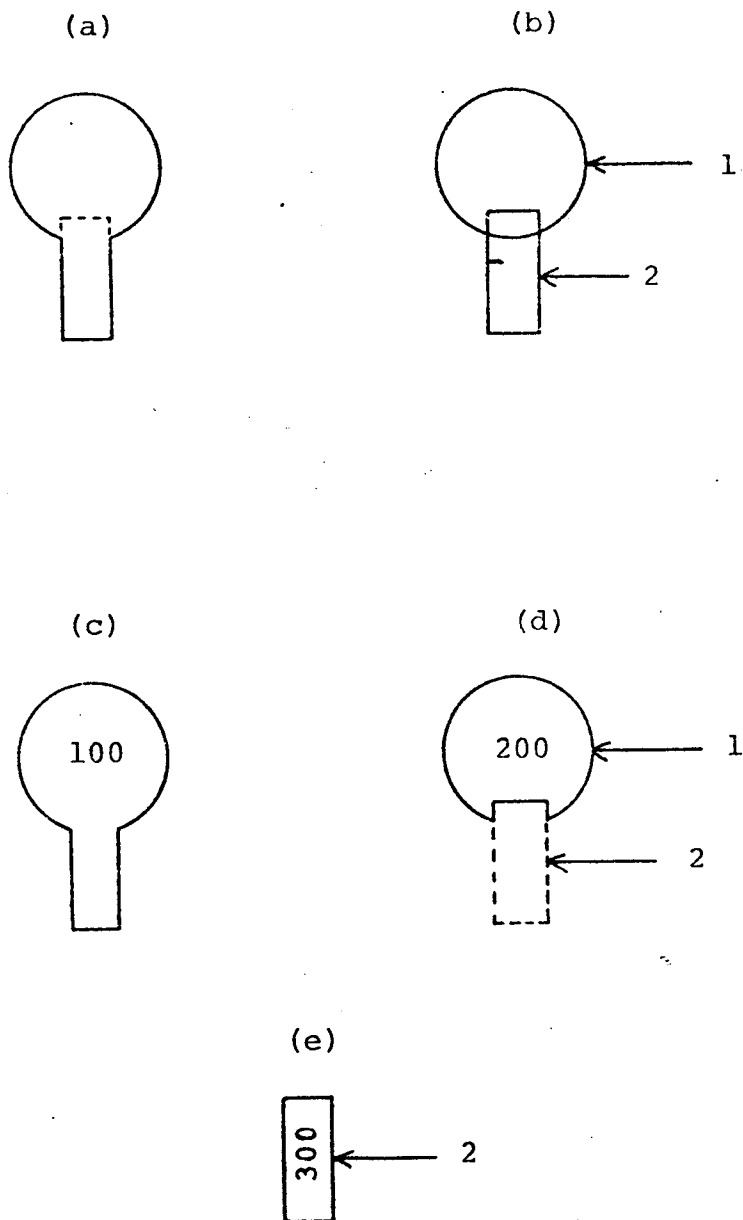


Figure 1 - Regions Produced by Intersections and Unions of Sphere and Cylinder

The description of region 200 would be {Fig. 1(d)}:

$$200 = (+1) (-2)$$

This means that points in region 200 are all those points inside body 1 which are not inside body 2.

The description of region 300 is simple {Fig. 1(e)}:

$$300 = (+2)$$

That is, all points in region 300 lie inside body 2.

This technique, of course, can be applied to combinations of more than two bodies and such region descriptions could conceivably contain a long string of (+), (-) and (OR) operators. The important thing to remember is that every spatial point in the geometry must be located in one and only one region. Further examples are given in Section 3.3.

3. PREPARATION OF CG INPUT

3.1 Introduction

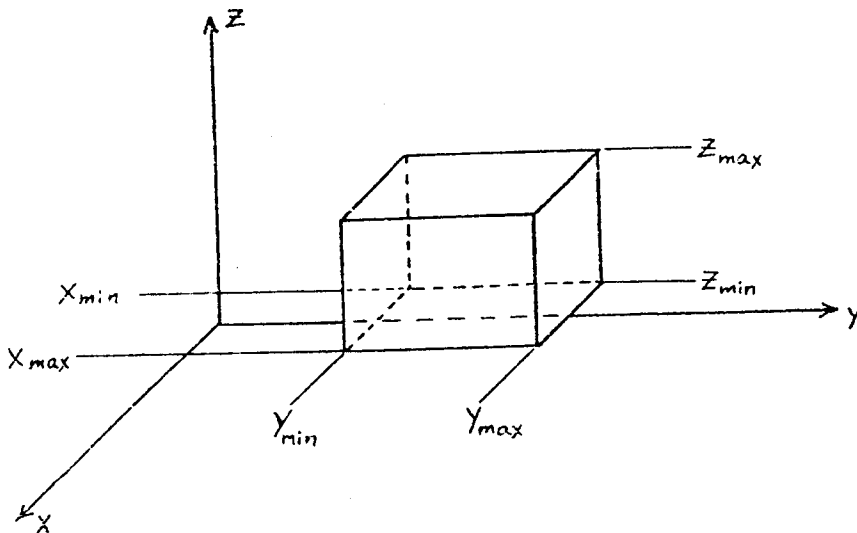
The user of the program will specify the geometry by establishing two tables. The first table will describe the type and location of the set of bodies used in the geometrical description. The second table will identify the physical region in terms of these bodies. The computer program processes these tables to put the data in the form required for ray tracing. All of the space must be divided into regions, and once again no point may be in more than one region.

3.2 Description of Body Parameters

The information required to specify each type of body is as follows.

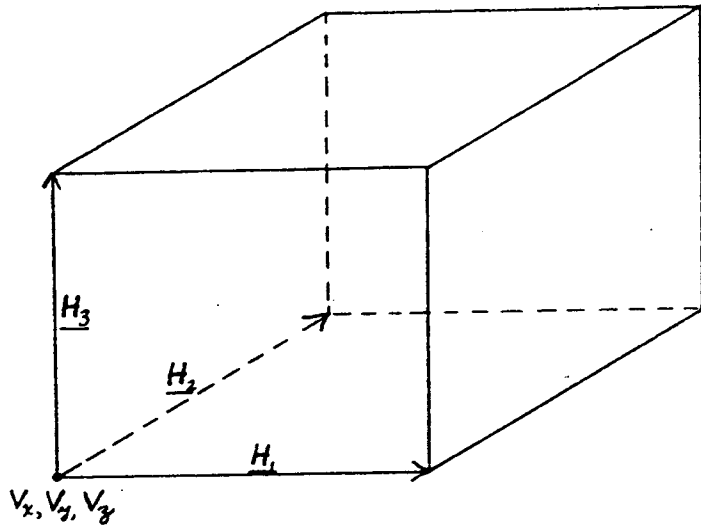
1. Rectangular Parallelepiped (RPP)

These bodies are used for gross subdivisions of the geometry and must have bounding surfaces parallel to the coordinate axes. Specify the maximum and minimum values of the x , y , and z coordinates which bound the parallelepiped.



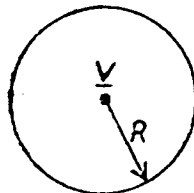
2. Box (BOX)

Specify the vertex \underline{V} at one of the corners by giving its (x,y,z) coordinates. Specify a set of three mutually perpendicular vectors, \underline{H}_i , representing the height, width, and length of the box, respectively. That is, the x,y , and z components of the height, width, and length vectors are given.



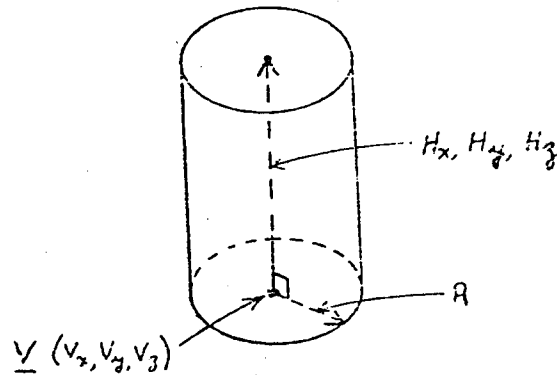
3. Sphere (SPH)

Specify the vertex \underline{V} at the center and the scalar, R , denoting the radius.



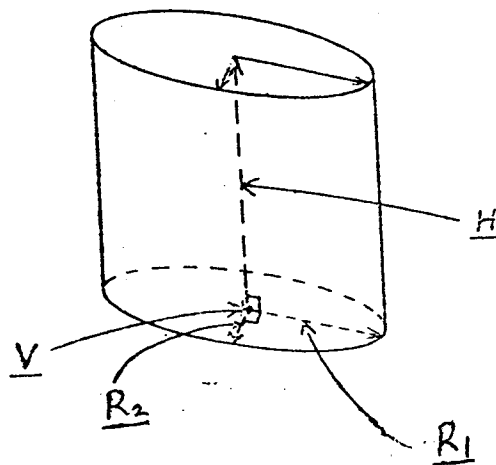
4. Right Circular Cylinder (RCC)

Specify the vertex \underline{V} at the center of one base, a height vector, \underline{H} , expressed in terms of its x , y , and z components, and a scalar, R , denoting the base radius.



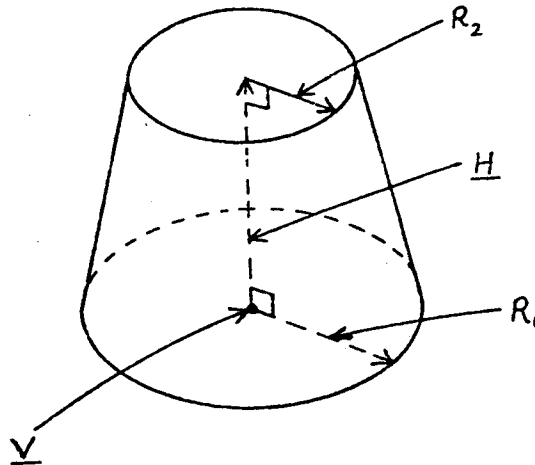
5. Right Elliptical Cylinder (REC)

Specify coordinates of the center of the base ellipse, a height vector, and two vectors in the plane of the base defining the semi-major and semi-minor axes, respectively.



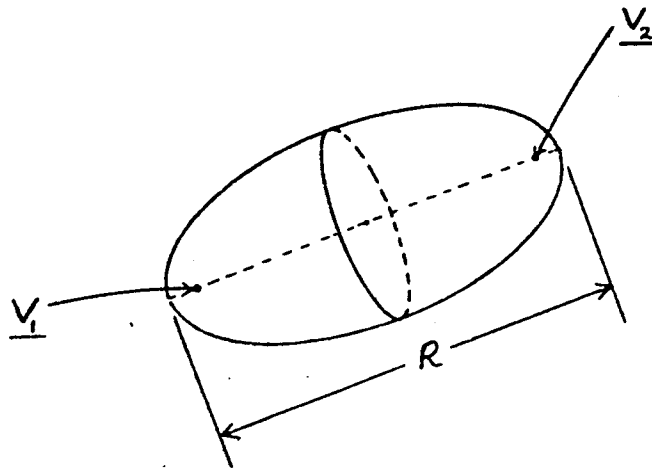
6. Truncated Right Angle Cone (TRC)

Specify a vertex \underline{V} at the center of the lower base, the height vector, \underline{H} , expressed in terms of its x, y, z components, and two scalars, R_1 and R_2 , denoting the radii of the lower and upper bases.



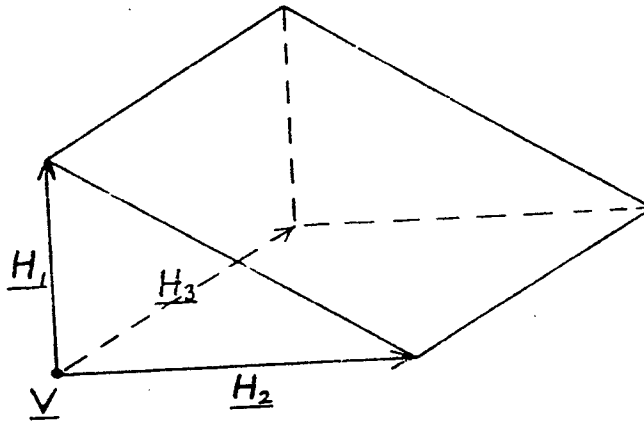
7. Ellipsoid (ELL)

Specify two vertices, \underline{V}_1 , denoting the coordinates of the foci and a scalar, R , denoting the length of the major axis.



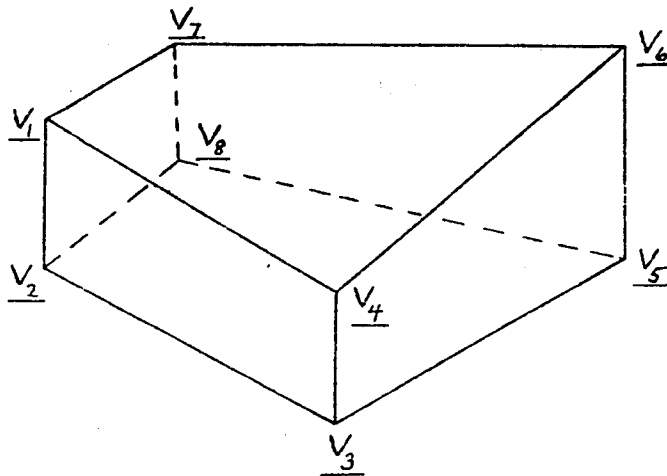
8. Right Angle Wedge (RAW)

Same input as for the boxes. However, H_1 and H_2 describe the two legs of the right triangle of the wedge.



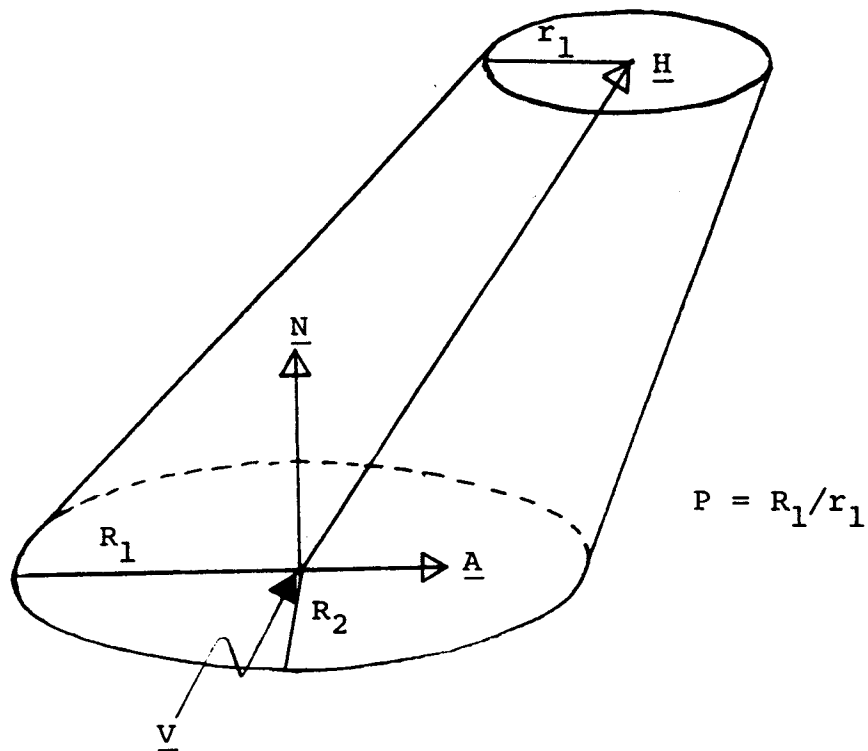
9. Arbitrary Polyhedron (ARB)

Assign an ordinal number (1 to 8) to each vertex. For each vertex, give the x, y, z coordinates. For each side of the figure list the ordinal vertex numbers. The vertices and side descriptions may be given in any order. An example is given later.



10. Truncated Elliptic Cone (TEC)

Specify the coordinates of the vertex \underline{V} at the center of the larger ellipse; the x , y , and z components of height vector \underline{H} ; the components of normal vector, \underline{N} , directed inward at \underline{V} ; the components of direction vector, \underline{A} , along major axis; the semi-major and semi-minor axes of larger ellipse, R_1 and R_2 , respectively; the ratio, P , of the larger to the smaller ellipse axis. Note that direction vectors \underline{N} and \underline{A} are normalized internally (after input printout).



3.3 Examples of Region Descriptions

Some representative geometries and their input descriptions are shown below.

Example 1 - Two Spheres Within an RPP (See Fig. 2)

The body input table is shown below.

TABLE I - BODY INPUT DESCRIPTION

<u>Body</u>	<u>Type of Data Required</u>
1	List the six bounding coordinate values (X_{\min} , X_{\max} , Y_{\min} , Y_{\max} , Z_{\min} , Z_{\max})
2	List the vertex and radius of sphere 2
3	List the vertex and radius of sphere 3

One possible region input table is shown below.

TABLE II - REGION DESCRIPTION

<u>Region</u>	<u>Input</u>
100	(+1) (-2) (-3) (Region 100 is composed of all points interior to RPP No. 1 and exterior to spheres 2 and 3)
200	(+3) (-2) (Region 200 is composed of all points interior to sphere 3 and exterior to sphere 2)
300	(+2) (+3) (Region 300 is composed of all points which are in sphere 2 and are also in sphere 3)
400	(+2) (-3) (Region 400 is composed of all points interior to sphere 2 and exterior to sphere 3)
500	(OR 2) (OR 3) (If desired, one region, the total of regions 200, 300, and 400, can be defined as region 500).

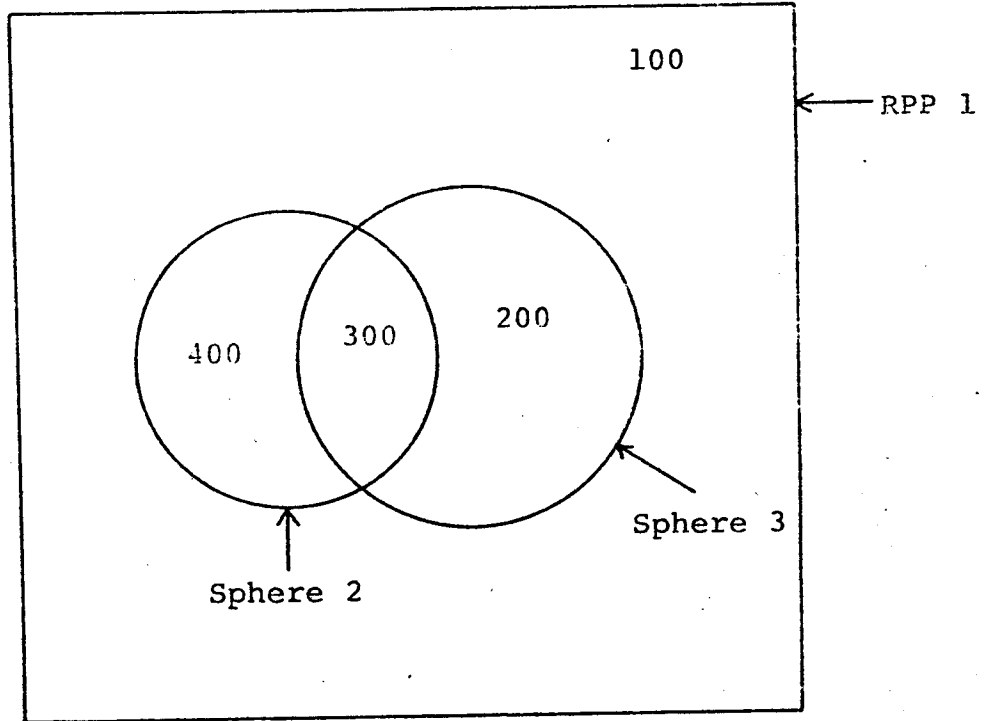


Figure 2 - Regions Produced by Intersections and Unions of Two Spheres

Example 2 - Cylinder Divided into Two Regions by a Box and with a Sphere at One End (See Fig. 3)

TABLE I - BODY INPUT DESCRIPTION

<u>Body</u>	<u>Type of Data Required</u>
1	List the six bounding coordinates of the RPP
2	List the vertex, radius, and height vector of cylinder
3	List center and radius of sphere
4	List coordinates of one corner and components of three vectors representing sides of box.

The region input is as follows.

TABLE II - REGION DESCRIPTION

<u>Region</u>	<u>Input</u>
100	(+1) (-2) (-3) (All points interior to the RPP and exterior to the cylinder and sphere. Note that region 100 includes all of the space contained inside body 4, except that portion inside cylinder 2. This space can be assigned a special region number, if desired. If, as in this example, it is not desired, it is not necessary).
200	(+2) (-4) (All points interior to the cylinder, and outside the box).
300	(+3) (-2) (All points interior to the sphere and external to the cylinder).
400	(+2) (+4) (All points interior to the cylinder and also inside the box).

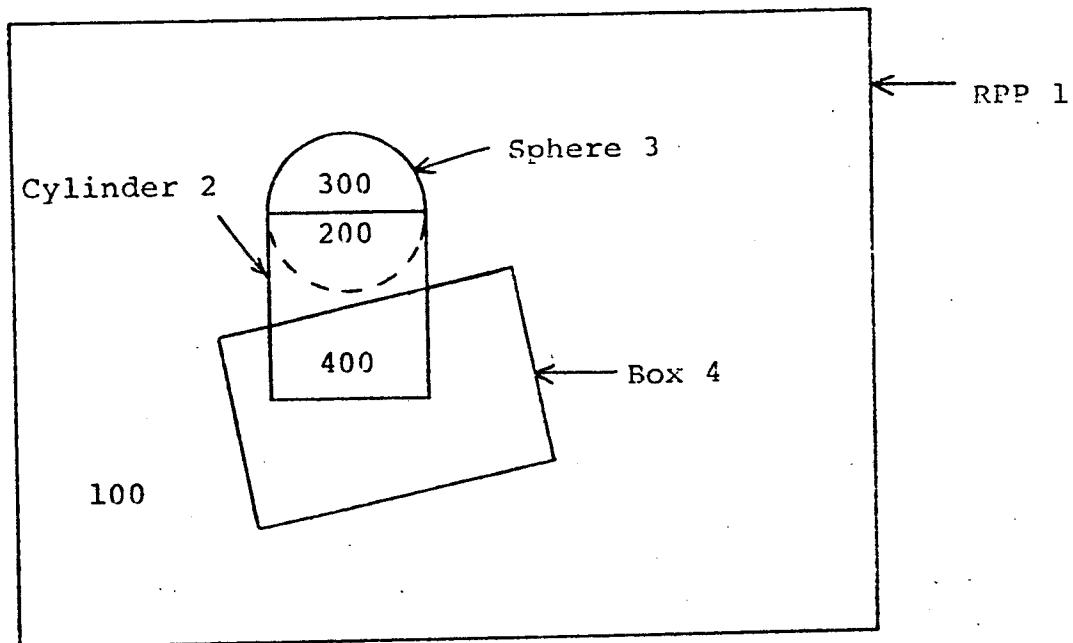


Figure 3 - Regions Produced by Intersections and Unions of Sphere, Circular Cylinder, and Box

Example 3 - Multiple Region Capability - Cylinder Containing
Two Spheres, All Inside an RPP (See Fig. 4)

TABLE I - BODY INPUT DESCRIPTION

<u>Body</u>	<u>Type of Data Required</u>
1	List RPP data
2	List cylinder input
3	List sphere input
4	List sphere input

TABLE II - REGION DESCRIPTION

<u>Region</u>	<u>Input</u>
100	(+1) (-2)
200	(OR 3) (OR 4) (All points interior to 3 or 4)
300	(+2) (-3) (-4) (All points in the cylinder but not in the spheres).

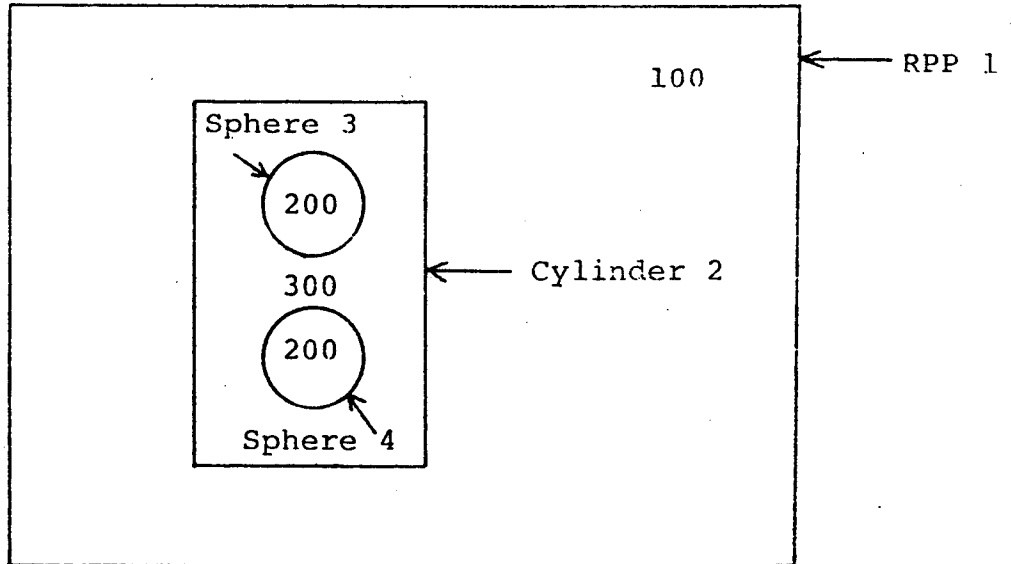


Figure 4 - Example of Physical Region Produced from Unconnected Regions Using "OR" Statement

3.4 Card Input Formats

The first card of a CG input deck is a header card:

FORMAT(I10,E15.4,A3,13A4)

<u>Columns</u>	<u>Item</u>	<u>Description</u>
1-10	IPRINT	= 0, print out body and region data which follow; = 1, print out body and region data, as well as the internal arrays in which they are stored; = 2, suppress geometry printout;
11-25	STRETCH	Scale factor for linear CG dimensions; a blank effects default (unity).
26-80	TITLE	55 arbitrary Hollerith characters.

The remainder of the CG input deck comprises body cards and region cards, which must appear in the order described below.

1. Body Cards

The computer assigns to each body an ordinal number which depends on the order in which the body cards are read in. Therefore, it is most important that the card sequence match the numbering sequence used in the region descriptions. Note that no gaps may be left in the body numbering sequence.

Ten different body types may be employed. The standard format for each body is as follows.

<u>Columns</u>	<u>Input</u>
1-2	Blank
3-5	Three-letter body identifier.
6	Blank

ColumnsInput

7-10	Four characters or arbitrary integer data
11-70	Divided into six floating point fields of 10 columns each. Body dimensions are given here.

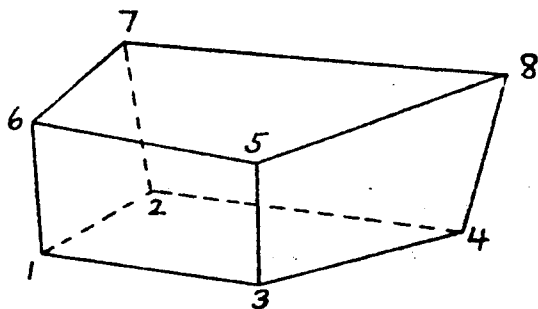
Table 1 describes the input required for each body. The quantities V, H, etc., were defined in Section 3.2.

Note that the last card of the body data must be END punched in columns 3, 4, 5. This is the signal that all body data have been treated.

TABLE I
LIST OF SURFACES FOR EACH BODY TYPE

Body Type	3-letter ID	Card Columns			Number of Cards Needed			
		11-20	21-30	31-40		41-50	51-60	61-70
Rectangular Parallelepiped	RPP	X _{min}	X _{max}	Y _{min}	Y _{max}	Z _{min}	Z _{max}	1
Box	BOX	Vx	Vy	Vz	H1x	H1y	H1z	1 of 2
		H2x	H2y	H2z	H3x	H3y	H3z	2 of 2
Sphere	SPH	Vx	Vy	Vz	R	-	-	1
Right Circular Cylinder	RCC	Vx	Vy	Vz	Hx	Hy	Hz	1 of 2
		R	-	-	-	-	-	2 of 2
Right Elliptic Cylinder	REC	Vx	Vy	Vz	Hx	Hy	Hz	1 of 2
		R1x	R1y	R1z	R2x	R2y	R2z	2 of 2
Ellipsoid of Revolution	ELL	V1x	V1y	V1z	V2x	V2y	V2z	1 of 2
		R	-	-	-	-	-	2 of 2
Truncated Cone	TRC	Vx	Vy	Vz	Hx	Hy	Hz	1 of 2
		R ₁	R ₂	-	-	-	-	2 of 2
Right Angle Wedge	RAW	Vx	Vy	Vz	H1x	H1y	H1z	1 of 2
		H2x	H2y	H2z	H3x	H3y	H3z	2 of 2
Arbitrary Polyhedron	ARB	V1x	V1y	V1z	V2x	V2y	V2z	1 of 5
		V3x	V3y	V3z	V4x	V4y	V4z	2 of 5
		V5x	V5y	V5z	V6x	V6y	V6z	3 of 5
		V7x	V7y	V7z	V8x	V8y	V8z	4 of 5
		Face Descriptions (See Note following page)						
Truncated Elliptic Cone	TEC	Vx	Vy	Vz	Hx	Hy	Hz	1 of 3
		Nx	Ny	Nz	Ax	Ay	Az	2 of 3
		R ₁	R ₂	P	-	-	-	3 of 3

Note: Each of the six faces of an ARB are described by a four-digit number giving the number of the four vertex points at the corners. The point numbers for each face must be entered in either clockwise or counterclockwise order. The format is 6(F10.0) starting in Column 11. An example is shown below.



FACE	1	2	3	4	5	6
PTS	1653.	3584.	4278.	1672.	1342.	5678.

Figure 5 - Example of Arbitrary Polyhedron

2. Region Cards

Each region must be numbered and described by a logical combination of the bodies which make up that region. Use as many cards as necessary to describe each region and begin each region on a new card. The input format, described below, is (2x, A3, 5x, 9 (A2, I5)).

ColumnsInput

1-2	Blank
3-5	Arbitrary Hollerith data
6-10	Blank
11-73	Divided into nine fields, of 7 columns each. The first two columns of each field are reserved for the OR operator. The third column is for the (+) or (-) operator. The last four columns are for the body number.

Use as many cards of the above type as needed to complete a region description, but leave Columns 1-10 blank on all continuation cards.

The last region description card must be followed by a card containing END in Columns 3, 4, and 5. This informs the code that all regions have been described.

4. THE CG CODE MODULE

4.1 Introduction

The CG code module comprises an executive routine, subordinate to a calling program such as LTHS, and the MAGI package of CG routines, including one which computes surface normals. Descriptions of every routine in this module, together with calling information, are given in this section.

4.2 Subroutine CGPACK

CGPACK is the executive routine of the CG module. It is the only link between the parent (calling) program and the CG routines. All communication with the calling program is made via two labeled common blocks: one for the information specified in the calling program, /GIVE/; the other for the information returned to the calling program, /TAKE/.

The function of CGPACK is to employ the CG routines such that the following information is returned to the calling program: Given a source ray (described by position coordinates and direction cosines) and a detector point, will the ray (a) miss, or (b) hit the target, as described by CG input; if (b), then (c) determine coordinates of-, CG region of-, direction to detector from-, and unit surface normal at-, the target position hit; and, if (b), will the reflected ray (d) "see" the detector point (i.e. the reflected ray will not be intercepted by another part of the target).

Thus, CGPACK acts as the proverbial "black box", which, given a source ray and detector point, governs the CG computations necessary to account for the purely geometric effects of a complex three-dimensional target.

The logical flow of CGPACK is given in Fig. 6, below.

CALLING INSTRUCTIONS

(a) Called from: parent program

CALL CGPACK

(b) Subroutines called: GENI

GETIR

GNORM

G1

(c) Variables required:

COMMON/GIVE/INT, IPT, IREX, IRTF, IRTL, XD(3), XS(3), WS(3)

INT - logical unit number for CG input
(usually 5);

IPT - logical unit number for printing
(usually 6);

IREX - escape region number, the outermost
region in CG input (usually defined
by an RPP surrounding a smaller RPP,
which in turn encloses all other CG bodies);

IRTF - first target region number (all target
regions must be input contiguously);

IRTL - last target region number;

XD(3) - coordinates of detector position;

XS(3) - coordinates of source position (fixed);

WS(3) - direction cosines of source ray;

Notes: (1) For a given execution, INT and IPT are
specified once.

(2) For a given CG input, IREX, IRTF, and
IRTL are fixed.

(3) For fixed source and detector, only source
direction cosines vary between calls to CGPACK.

(d) Variables returned:

COMMON/TAKE/MKH, IRT, XT(3), WT(3), WN(3)

MKH - (miss, kill, hit) target flag
(see Notes below);

IRT - region number of target position
hit (MKH_>0);

XT(3) - coordinates of target position
hit (MKH_>0);

WT(3) - direction cosines of unit vector
at XT(3) toward detector (MKH_>0);

WN(3) - direction cosines of outward
normal at XT(3) (MKH_>0);

Notes: (1) MKH = -1, source ray missed the target.

(2) MKH = 0, source ray hit target, but
reflected ray subsequently killed along
track to detector, by intersecting
another target position.

(3) MKH = 1, source ray hit target, and
reflected ray reached detector.

Figure 6 - CGPACK Logical Flow

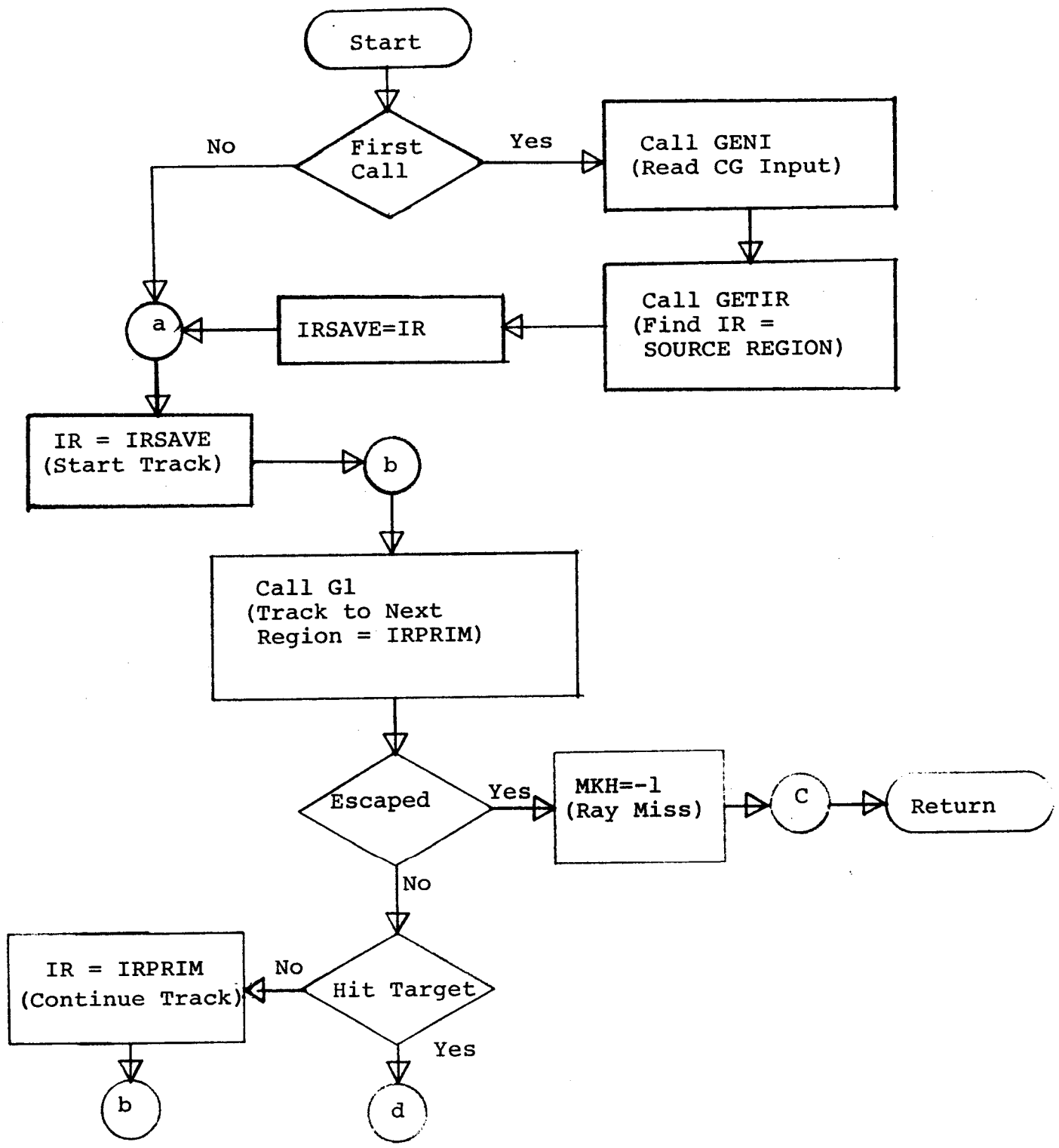
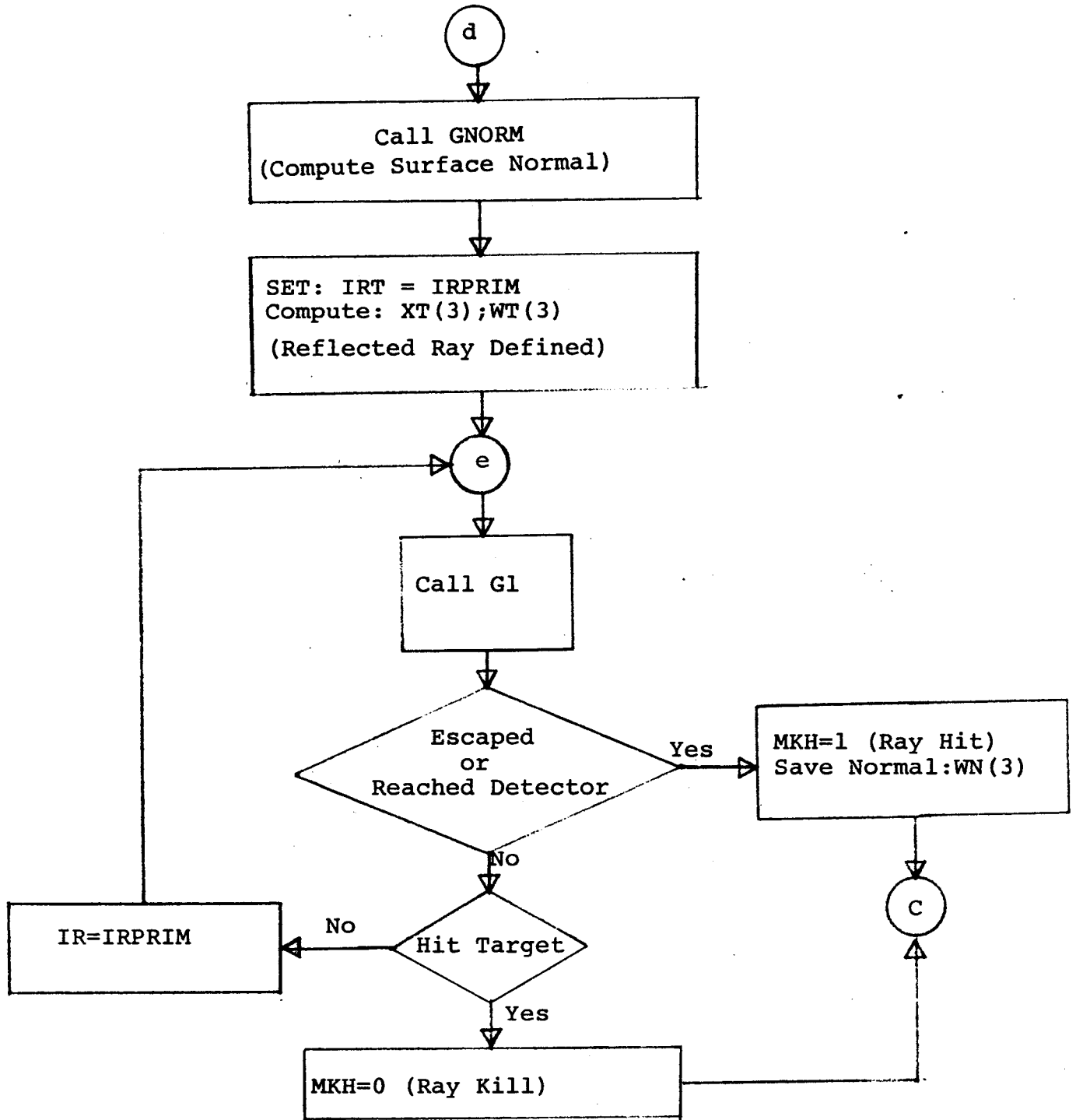


Figure 6 - Continued



4.3 Subroutine GENI

GENI is the principal CG input processing routine. It reads in the CG data, checks for errors, and stores the data into a fixed point and floating point array, MA and FPD, respectively, in the form required by the tracking routines. For an ARB body type (see Section 3.2), GENI calls GARB for additional processing. An option has been implemented which allows the unit of the linear body dimensions to be altered by a user supplied scaling factor (see description of header card in Section 3.4). The default unit is the one utilized in preparing the input deck (i.e. scaling factor equals unity).

CALLING INSTRUCTIONS

(a) Called from: CGPACK

CALL GENI

(b) Subroutine called: GARB

(c) Principal variables required:

IN - logical unit number for CG input;

IOUT- logical unit number for printing;

(d) Principal variables returned:

EPS - internally computed smallest number
such that $(1.+EPS) > 1.$

(i.e. "machine epsilon");

MA(I) - CG integer array

FPD(I) -CG floating point array

4.4 Subroutine GARB

GARB is an auxiliary input processing routine, called by GENI whenever an ARB body type is encountered on input. GARB accepts

the originally specified ARB input data read by GENI (see Table 1), and computes a unit normal vector and a minimum distance to the origin for each plane containing a side of the ARB. These data are then stored in the locations of the FPD array used to store the original data. The number of ARB sides (up to six), and a scalar characteristic of the ARB's minimum dimension (used for round-off tests) are also stored in the FPD array.

CALLING INSTRUCTIONS

- (a) Called from: GENI
CALL GARB (FPD(LF), IERR)
- (b) Subroutines called: none
- (c) Principal variables required:
F - FPD array read in GENI
- (d) Principal variables returned:
F - FPD array, modified as described above.

4.5 Subroutine G1

G1 is the principal CG tracking routine. Given a position and direction of a ray, and the current region number, G1 will compute the distance tracked in the current region, the cumulative distance tracked from start of trajectory, and the next region number encountered. G1 also determines the body number, whose surface defines the region (exit) boundary, and that surface number (negative if leaving and positive if entering body).

CALLING INSTRUCTIONS

- (a) Called from: CGPACK
CALL G1(S)

(b) Subroutines called: GG

GGTEC

GP (for debugging only)

(c) Principal variables required:

XB(3) - position coordinates at start of track;

WB(3) - direction cosines of ray;

IR - current region number;

DIST - cumulative distance traveled from
XB(3);

NASC - flags the start of a new track if
negative;

KLOOP - counter of new tracks;

(d) Principal variables returned:

KLOOP - incremented for a new track;

NASC - body number whose surface defines
region (exit) boundary;

LSURF - surface of body NASC crossed at region
boundary;

S - distance tracked in region IR;

DIST - incremented by S;

IRPRIM - region number entered upon crossing
LSURF of body NASC.

4.6 Subroutine GG

GG is the distance calculating routine for all body types except the TEC, which is handled by GGTEC. Given a position and direction of a ray, and a body number, GG computes the distance to entry, RIN, and the distance to exit, ROUT, measured from the given position coordinates of the ray.

RIN and ROUT are then stored in the FPD array, at the locations set aside for this body. GG also stores the indices for the entry and exit surfaces of the body, LRI and LRO, respectively, in the MA array. As a time saving device, the track counter KLOOP is also saved, so that any subsequent call to GG, for the same body and KLOOP value, will bypass the computations of RIN and ROUT, and retrieve the previously computed values from the FPD array.

CALLING INSTRUCTIONS

(a) Called from: G1

GETIR

CALL GG(LOCAT)

(b) Subroutines called: none

(c) Principal variables required:

LOCAT - pointer for integer data in MA
array for the body;

KLOOP - track counter;

(d) Principal variables returned:

RIN - distance to body entry;

ROUT - distance to body exit;

LRI - entry surface;

LRO - exit surface;

4.7 Subroutine GGTEC

GGTEC performs the identical functions for the TEC body as GG does for all other body types.

4.8 Subroutine GETIR

GETIR determines the region number IR corresponding to a given set of position coordinates and (arbitrary) direction cosines.

This function is performed for a source ray, similar to the manner in which G1 determines the region number encountered at a boundary crossing.

CALLING INSTRUCTIONS

- (a) Called from: CGPACK
CALL GETIR
- (b) Subroutines called: GG
GGTEC
- (c) Principal variables required:
XB(3) - position coordinates for which
region number is required;
WB(3) - arbitrary direction cosines;
- (d) Principal variables returned:
IR - region number for point XB(3);

4.9 Subroutine GNORM

GNORM computes the unit normal vector to the target surface struck by the source ray*. The surface point struck is computed by tracing the cumulative distance tracked by G1, DIST, along the source direction from the source point. The sign of the normal is chosen so that it is oriented opposite to the source ray direction.

CALLING INSTRUCTIONS

- (a) Called from: CGPACK
- (b) Subroutines called: none
- (c) Principal variables required:
XB(3) - position at start of track
(equal to source position coordinates);

*Several algorithms were borrowed from the MORSE Code³.

WB(3) - source direction cosines;
DIST - distance to target point struck;
NASC - body number struck;
LSURF - surface of NASC struck;

(d) Principal variables returned:

UN(3) - direction cosines of unit normal;

4.10 Subroutine GP

GP is a debug printout routine. It can only be utilized by G1 if the variable IDBG is not set to zero. Since this option is not utilized during normal execution, IDBG has been set to zero in CGPACK.

5. SUMMARY

The CG code module, described herein, comprises an efficient software package for the geometric modeling of complex three-dimensional targets, such as a Russian T-54 tank (see CG input listing in Appendix B). The minimal required interfacing with the parent code, via two labeled common blocks, makes this module a highly adaptable "black box."

REFERENCES

1. M. O. Cohen, et al, "SAM-CE: A Three Dimensional Monte Carlo Code for the Solution of the Forward Neutron and Forward and Adjoint Gamma Ray Transport Equations, Revision A", DNA 2830F, Rev. A, MR-7021, Rev. A (July 1972).
2. S. Hui, et al, "SAMCEP: An Application of Correlated Monte Carlo to the Simultaneous Solution of Multiple, Perturbed, Time-Dependent Neutron Transport Problems in Complex Three-Dimensional Geometry", BRL CR62, MR-7020 (January 1972).
3. E. A. Straker, et al, "The MORSE Code with Combinatorial Geometry", DNA 2860T, SAI-72-511-LJ (May 1972).

APPENDIX A

CG MODULE (LISTING)

```

MEMBER NAME CGPACK
SUBROUTINE CGPACK
COMMON/GIVE/INT,IPT,IREX,IRTF,IRTL,XD(3),XS(3),WS(3)
C----- INT=LOGICAL UNIT FOR GEOMETRY INPUT ( USUALLY 5).
C----- IPT=LOGICAL UNIT FOR PRINTER ( USUALLY 6).
C----- IREX=ESCAPE REGION.
C----- IRTF=FIRST TARGET REGION.
C----- IRTL=LAST TARGET REGION, WHERE ALL TARGET REGIONS INPUT CONTIGU.
C----- XD(3)=COORDINATES OF DETECTOR POSITION.
C----- XS(3)=COORDINATES OF SOURCE POSITION.
C----- WS(3)=DIRECTION COSINES OF SOURCE RAY.
COMMON/TAKE/MKH,IRT,XT(3),WT(3),WN(3)
C----- MKH=MISS, KILL, HIT TARGET FLAG.
C----- IRT=TARGET REGION OF INITIAL HIT.
C----- XT(3)=COORDINATES OF TARGET HIT.
C----- WT(3)=DIRECTION COSINES TOWARD DETECTOR AT XT(3).
C----- WN(3)=DIRECTION COSINES OF OUTWARD NORMAL AT XT(3).
COMMON/NORMAL/UN(3)
COMMON/GEOM3/EPS,IRHA(200)
COMMON/PAREM /XB(3) ,WB(3) ,E ,IR ,T ,IDET ,F , PAREM
1 NHIST ,WC ,J12345 ,WP(3) ,XP(3) ,EPRIM ,ATWT , PAREM
2 NCDB ,CSTHT ,U ,LCHI ,IATWT ,IERR ,IDBG , PAREM
3, IRPRIM,NASC ,LSURF ,NBD ,LRI ,LPO ,KIN , PAREM
4 ROUT ,KLOOP ,LOOP ,ITYPE ,PINF ,NOA ,DIST
COMMON/TAPE /IN ,IOUT ,IEDT ,INT1 ,INT2 ,IAGG,ITRAN,INTER TAPE IN
DATA IFIRST/0/
IF(IFIRST.NE.0)GO TO 100
IN=INT
IOUT=IPT
IDRG=C
CALL GENI
EP=1.0-10.0*EPS
100 DO 110 I=1,3
WB(I)=WS(I)
110 XB(I)=XS(I)
IF(IFIRST.NE.0)GO TO 113
CALL GETIR
IPSAVE=IR
IFIRST=1
GO TO 115
113 IP=IPSAVE
115 NASC=-1
120 CALL G1(S)
IF(IRPRIM.EQ.IREX)GO TO 700
IF(IRTF.LE.IRPRIM.AND.IRPRIM.LE.IRTL)GO TO 200
C----- HAVE NOT HIT TARGET YET.
IR=IRPRIM
GO TO 120
C----- INITIAL HIT OF TARGET.
200 CALL GNORM
IRT=IRPRIM
DIS=EP*DIST
DO 210 I=1,3
XB(I)=XB(I)&DIS#WB(I)
XT(I)=XB(I)
210 WB(I)=XD(I)-XB(I)
DISD=SQRT(WB(1)**2&WB(2)**2&WB(3)**2)
DO 220 I=1,3
WB(I)=WB(I)/DISD

```

MEMBER NAME CGPACK

220 WT(I)=WB(I)

NASC=-1

230 CALL G1(S)

IF(IRPRIM.EQ.IREX.OR.DIST.GE.DISD)GO TO 900

IF(IRTF.LE.IRPRIM.AND.IRPRIM.LE.IRTL)GO TO 800

IR=IRPRIM

GO TO 230

C-----RAY MISSED TARGET.

700 MKH=-1

GO TO 1000

C-----RAY HIT TARGET AFTER REFLECTION.

800 MKH=0

GO TO 1000

C-----RAY REACHED DETECTOR.

900 MKH=1

DO 91C I=1,3

910 WN(I)=UN(I)

1000 RETURN

END

MEMBER NAME GARB

SUBROUTINE GARB (F,IERR).

NEW NAME FOR SUBROUTINE ALBERT

COMMON/JAN2637DATEX

DIMENSION F(9),X(3,8),IX(4,6),V(3,4)

COMMON/ GEOM4/ IPRINT

COMMON/TAPE /INT ,IOUT ,IEDT ,INT1 ,INT2 ,IAGG,ITRAN,INTER TAPE

DO 10 I=1,8

DO 10 J=1,3

K=3*(I-1)&J

X(J,I)=F(K)

10 F(K)=0.

IPMAX=0

DO 40 I=1,6

K=0

NSIDE=I-1

M=F(I&24)

DO 20 J=1,4

IX(J,I)=M-(M/10)*10

IF(IX(J,I).NE.0) K=K&1

IF(IX(J,I).GT.IPMAX) IPMAX=IX(J,I)

20 M=M/10

IF(K.EQ.0) GO TO 50

IF(K.GE.3) GO TO 40

WRITE(IOUT,22) I,J,F(I&24)

22 FORMAT(26H ERROR IN SIDE DESCRIPTION,2I10,F10.0)

GO TO 200

40 CONTINUE

NSIDE=6

FIND MINIMUM DISTANCE BETWEEN POINTS

50 DMIN=1.0E&20

IPMAX=IPMAX-1

DO 60 I=1,IPMAX

DO 60 J=I,IPMAX

D=(X(1,I)-X(1,J&1))**2&(X(2,I)-X(2,J&1))**2&(X(3,I)-X(3,J&1))**2

IF((D.GT.0).AND.(D.LT.DMIN)) DMIN=D

60 CONTINUE

DMIN=0.5*SQRT(DMIN)

IPMAX=IPMAX&1

DO 100 I=1,NSIDE

J1= IX(3,I)

DO 62 J=2,4,2

J2= IX(J,I)

DO 62 K=1,3

62 V(K,J) = X(K,J1) - X(K,J2)

A= V(2,2)*V(3,4) - V(3,2)*V(2,4)

B= V(3,2)*V(1,4) - V(1,2)*V(3,4)

C= V(1,2)*V(2,4) - V(2,2)*V(1,4)

D=-(A*X(1,J1)& B*X(2,J1)& C*X(3,J1))

EPS= SQRT(A*A & B*B & C*C)

NPL=C

NMI=0

DO 80 J=1,IPMAX

DS=(A*X(1,J) & B*X(2,J) & C*X(3,J) & D)/EPS

```

MEMBER NAME GARB
ADS=ABS(DS)
IF(ADS.GT.DMIN)GO TO 70
IF(ADS.LT.0.01*DMIN)GO TO 80
WRITE(IOUT,65)F(I&24)
55 FORMAT(32HOVERTICES NOT CO-PLANER FOR FACE,E15.7//)
70 IF(DS.GT.0.0)GO TO 74
NMI=NMI&1
GO TO 80
74 NPL=NPL&1
80 CONTINUE
IF( (NMI.EQ.0).AND.(NPL.GT.0)) GO TO 90
EPS=-EPS
IF( (NPL.EQ.0).AND.(NMI.GT.0))GO TO 90
IERP=IERR&1
WRITE(IOUT,85) I,NMI,NPL,F(I&24),A,B,C,D
85 FORMAT(26H ERROR IN FACE DESCRIPTION,3I10/5E15.7 )
GO TO 200
90 F( 4*I-3)=A/EPS
F( 4*I-2)=B/EPS
F( 4*I-1)=C/EPS
F( 4*I )=D/EPS
100 CONTINUE
F(25)=NSIDE
F(26)=DMIN
IF(IPRINT.NE.2) WRITE(IOUT,195) (F(I),I=1,26)
195 FORMAT( 30X,4E15.7 )
200 RETURN
END

```

```

MEMBER NAME GENI
SUBROUTINE GEVI
DIMENSION IBIAS(10),ITY(11),IJ(21),IK(21)
COMMON / GEOM2 /-LBCREG(200),NUMBOD(200),IROR(200),MA(4000),
1 FPD(4000),LDATA,NUMB,NUMR
COMMON/GEOM3/EPS,IRHA(200)
COMMON/ GEOM4/ IPRINT
COMMON/PAREM /XB(3) ,WB(3) ,E ,IR ,T ,IDET ,F , PAREM
1 V-I ST ,WC ,J12345 ,WP(3) ,XP(3) ,EPRIM ,ATWT , PAREM
2 NCJB ,CSTHT ,U ,LCHI ,IATWT ,IERR ,IOBG , PAREM
3, IRPRIM,NA SC ,LSURF ,NBO ,LRI ,LRO ,RIN , PAREM
4 RJUT ,KLOOP ,LOOP ,ITYPE ,PINF ,NOA ,DIST
COMMON/TAPE /IV ,IOUT ,IEDT ,INT1 ,INT2 ,IAGG,ITRAN,INTER TAPE IN
EQUIVALENCE(IBIAS,IK),(ITY,IK(11))
C 1 2 3 4 5 6 7 8 9 10 11
C ARB SPH RCC REC TRC ELL BOX WED RPP TEC END
C 24 -2 -1 6 2 1 6 6 0 9
DATA IJ / 24,-2,1,6,2,1,6,6,0,9,
1 3HARB,3HSPH,3HRCC,3HREC,3HTRC,3HELL,3HBOX,3HWED,3HRPP,
2 3HTEC,3HEND/
C-----RAW AND WED ARE SAME BODY.
DATA IRAW,IWED/3HRAW,3HWED/
DATA IOR,IBL,IEVD/2HOR,3H ,3HFND/
C-----COMPUTE MACHINE EPS.
EPS=1.0
DO 10 I=1,100
EPS=EPS/2.0
IEPS=I
IF((1.0&EPS).EQ.1.0)GO TO 11
10 CONTINUE
11 EPS=2.0*EPS
IEPS=IEPS-1
WRITE(IOUT,12)EPS,IEPS
12 FORMAT(13HOMACHINE EPS=E13.6,5H= 2(-I2,1H)/)
C-----SET WB FOR GETIR.
WB(1)=1.0/SQRT(3.0)
WB(2)=WB(1)
WB(3)=WB(1)
PINF=1.0E&20
KLOOP=0
READ(IN,70) IPRINT,STRECH, (MA(I), I=1,14)
CC IPRINT=0 BODY AND REGIONS ONLY, =1 ALL DATA, =2 NO DATA.
70 FORMAT(I10,E15.4,A3,13A4)
IF(STRECH.EQ.0.) STRECH=1.0
WRITE(IOUT,75) STRECH, (MA(I), I=1,14)
75 FORMAT(16H STRETCH FACTOR=,E15.4,/,2X,A3,13A4)
C
C CLEAR GEOMETRY ARRAYS
DO 76 I=1,21
76 IK(I)=IJ(I)
LFPD=4000
LMA=4000
DO 80 I=1,LFPD
80 FPD(I)=0.
DO 85 I=1,LMA
85 MA(I)=0
IF(IPRINT.EQ.2) GO TO 87
C
WRITE(IOUT,86)

```

A

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6/73
6/73
6/73

6/73
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MEMBER NAME GENI

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```
86 FORMAT(//50X,9H3JJDY DATA)
87 N=1
   L2=2
   M=0
90 L1=L2&1
   LF=L1
   L2=L1&5
   M=M&1
   READ( IN,100) ITYPE,IALP,(FPD(I),I=L1,L2)
100 FORMAT(2X,A3,1X,A4,6E10.3)
   IF(STRECH.EQ.1.0) GO TO 102
   DO 101 I=L1,L2
101 FPD(I)=FPD(I)*STRECH
102 IF(IPRINT.EQ.2) GO TO 107
   WRITE(IOUT,105) ITYPE,IALP,(FPD(I),I=L1,L2),L1,M
105 FORMAT(2X,A3,1X,A4,6E15.7,I5,2H B,I4)
107 IF(ITYPE.EQ.IRAW) ITYPE=IWED
   DO 110 I=1,11
   IF( ITY(I).EQ.ITYPE ) GO TO 120
110 CONTINUE
   STOP
120 IF( I.EQ.11) GO TO 160
   MORE=IBIAS(I)
   MA(N)=IALP
   MA(N&2)=I
   MA(N&6)=L1-2
   N=N&7
   IF( MORE.LE.0) GO TO 150
   L1=L2&1
   L2=L1&MORE-1
   READ(IN,130) (FPD(I),I=L1,L2)
130 FORMAT( 10X,6E10.3)
   IF(STRECH.EQ.1.0) GO TO 135
   L2X=L2
   IF(ITYPE.EQ.ITY(1)) L2X=L2X-6
CC FOR ARBS, THE LAST 6 ENTRIES ARE FACE DESCRIPTIONS, NOT DIMENSIONS
   IF(ITYPE.EQ.ITY(10)) L2X=L2X-1
C-----LAST TEC ENTRY IS RATIO. N AND A NORMALIZED BELOW.
   DO 132 I=L1,L2X
132 FPD(I)=FPD(I)*STRECH
135 IF(IPRINT.EQ.2) GO TO 150
   WRITE(IOUT,140) ( FPD(I),I=L1,L2)
140 FORMAT(10X,6E15.7)
150 L2=L2&2
   IF(ITYPE.EQ.ITY(1)) CALL GARB(FPD(LF),IERR)
   IF(ITYPE.NE.ITY(10)) GO TO 90
C-----NORMALIZE N AND A VECTORS.
   L2=L2&9
   LF=LF-2
   Z=1./SQRT(FPD(LF&8)**2&FPD(LF&9)**2&FPD(LF&10)**2)
   FPD(LF&8)=Z*FPD(LF&8)
   FPD(LF&9)=Z*FPD(LF&9)
   FPD(LF&10)=Z*FPD(LF&10)
   Z=1./SQRT(FPD(LF&11)**2&FPD(LF&12)**2&FPD(LF&13)**2)
   FPD(LF&11)=Z*FPD(LF&11)
   FPD(LF&12)=Z*FPD(LF&12)
   FPD(LF&13)=Z*FPD(LF&13)
C-----PRECOMPUTE TEC CONSTANTS AND STORE IN FPD ARRAY.
```


MEMBER NAME GENI

```
FPD(LF&17)=FPD(LF&12)*FPD(LF&10)-FPD(LF&13)*FPD(LF&9)
FPD(LF&18)=FPD(LF&13)*FPD(LF&8)-FPD(LF&11)*FPD(LF&10)
FPD(LF&19)=FPD(LF&11)*FPD(LF&9)-FPD(LF&12)*FPD(LF&8)
FPD(LF&20)=FPD(LF&5)*FPD(LF&11)&FPD(LF&6)*FPD(LF&12)
1      &FPD(LF&7)*FPD(LF&13)
FPD(LF&21)=FPD(LF&5)*FPD(LF&8)&FPD(LF&6)*FPD(LF&9)
1      &FPD(LF&7)*FPD(LF&10)
FPD(LF&22)=FPD(LF&5)*FPD(LF&17)&FPD(LF&6)*FPD(LF&13)&
1      FPD(LF&7)*FPD(LF&19)
FPD(LF&23)=(FPD(LF&14)/FPD(LF&15))**2
D=1.0/FPD(LF&16) - 1.0
FPD(LF&24)=FPD(LF&23)*(FPD(LF&15)*D)**2
FPD(LF&25)=FPD(LF&21)*FPD(LF&8)&FPD(LF&3)*FPD(LF&9)
1      &FPD(LF&4)*FPD(LF&10)
```

K3

HDA

HDN

HDK

TAU

VDN

```
GO TO 90
160 NUMB=N/7
WRITE(IOUT,170) NUMB,N,L2
170 FORMAT(20H NUMBER OF BODIES ,15,
1      / 20H LENGTH OF MA-ARRAY ,15,
2      / 20H LENGTH OF FPD-ARRAY ,15 )
```

C
C END OF BODY DATA
C

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```
IF(IPRINT.NE.1) GO TO 176
WRITE(IOUT,172)
172 FORMAT( 50X,9HFPD ARRAY)
DO 174 I=1,L2,5
K=I&4
174 WRITE( IOUT,175) I,(FPD(J),J=I,K),K
175 FORMAT( 15,5E20.7,15 )
176 IF(IPRINT.EQ.2) GO TO 182
WRITE(IOUT,180)
180 FORMAT(//50X,11HREGION DATA)
182 IRTRU=0
IR=0
IR1=0
190 K=1
READ(IN,200) IALP,( IBIAS(I),ITY(I),I=1,9 )
IF(IALP.NE.IBL)IR1=IR1&1
IF(IPRINT.EQ.2) GO TO 206
WRITE(IOUT,205) IALP,( IBIAS(I),ITY(I),I=1,9),IR1
200 FORMAT(2X,A3,5X,9(A2,I5))
205 FORMAT(2X,A3,5X,9(A2,I5),2X,14R,I3)
206 IF( IALP.EQ.IBL ) GO TO 220
IF(IRTRU.NE.0)IR4A(IRTRU)=IR
IF( IALP.EQ.IEN) GO TO 300
IRTRU=IRTRU&1
210 IR=IR&1
LJCREG(IR)=N
NUMBOD(IR)=1
IROR(IR)=IRTRU
MA(N)=IALP
MA(N&1)=ITY(K)
MA(N&2)=7*IABS(ITY(K))-6
N=N&5
K=K&1
IF(K.GT.9)GO TO 190
220 KL=K
```

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MEMBER NAME GENI

DO 230 I=KL,9

K=I

IF(IBIAS(I).EQ.IOR) GO TO 210

IF(ITY(I).EQ.0) GO TO 190

MA(N)=ITY(K)

MA(N&1)= 7*IABS(ITY(K))-6

N=N&4

NUMBOD(IR)=NUMBOD(IR)&1

230 CONTINUE

GO TO 190

300 CONTINUE

LDATA=N

NUMR=IR

WRITE(IOUT,310) IRTRU,IP,N

310 FORMAT(24H NUMBER OF INPUT REGIONS ,I5

1 / 24H NUMBER OF CODE REGIONS ,I5

2 / 24H LENGTH OF INTEGER ARRAY ,I5)

IF(IPRINT.NE.1) GO TO 327

WRITE(IOUT,315)

315 FORMAT(/54HOCODE REGION LOC. OF REG. DATA NO. OF BODIES INPUT REG)

WRITE(IOUT,317) (I,LOCREG(I),NUMBOD(I),IROR(I),I=1,NUMR)

317 FORMAT(I12,I18,I14,I10)

WRITE(IOUT,320)

320 FORMAT(50X,10H MA -ARRAY)

DO 325 I=1,LDATA,10

K=I&9

325 WRITE(IOUT,326) I,(MA(J),J=I,K),K

326 FORMAT(I5,I10,9I5,I10)

6/71

C

C END OF REGION DATA

C

327 RETURN

END

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```

MEMBER NAME GETIR
SUBROUTINE GETIR
C FINDS REGION NUMBER FOR POINT XB
C NEEDS GG AND GENI
LOGICAL LOGG
DIMENSION IRS(10)
COMMON / GEOM2 / LOCREG(200),NUMBOD(200),IROR(200),MA(4000),
1 FPD(4000),LDATA,NUMB,NUMR
COMMON/PAREM /XB(3),WB(3),E,IR,T,IDET,F,PAREM
1 NLIST,WC,J12345,WP(3),XP(3),EPRIM,ATWT,PAREM
2 NCDB,CSTHT,U,LCHI,IATWT,IERR,ICBG,PAREM
3, IRPRIM,NASC,LSURF,NBO,LRI,LRO,FIN,PAREM
4 RJUT,KLOOP,LOOP,ITYPE,PINF,NOA,DIST
COMMON/TAPE /INT,IOUT,IEDT,INT1,INT2,IAGG,ITRAN,INTER TAPE
KLOOP=KLOOP&1
L=0
DO 700 IRP=1,NUMR
N=LOCREG(IRP)&1
NUM=NUMBOD(IRP)*4&N-4
DO 650 I=N,NUM,4
NBO=MA(I)
LOCAT=MA(I&1)
ITYPE=MA(LOCAT&2)
IF(ITYPE.NE.10)CALL GG(LOCAT)
IF(ITYPE.EQ.10)CALL GGTEC(LOCAT)
LOGG=(ROUT.LE.0.).OR.(RIN.GT.0.)
IF(NBO)620,650,630
620 LOGG=.NOT.LOGG
630 IF(LOGG)GOTO700
650 CONTINUE
IR=IROR(IRP)
IF(L.NE.0.AND.IR.EQ.IRS(L))GOTO700
L=L&1
IRS(L)=IR
IF(L.GE.10)GOTO300
700 CONTINUE
IF(L-1)200,5000,300
300 WRITE(IOUT,101)XB,L,(IRS(K),K=1,L)
101 FORMAT(19HOREGION OVERLAP FOR 3E20.7/I3,8H REGIONS 10I10)
GO TO 5000
200 IR=0
WRITE(IOUT,100) XB
100 FORMAT(21HOREGION NOT FOUND FOR 3E20.7)
5000 RETURN
END

```

```

MEMBER NAME GG
SUBROUTINE GG(LJCAT)
COMMON/JAN233 / DATEX
CC WEDGE BUG CORRECTED BY MOC
DIMENSION ASQ(3),PV(3),G(3)
DIMENSION VHAB(12),V(3),H(3),A(3),B(3)
DIMENSION IBOX(3)
COMMON / GEOM2 / LDCREG(200),NUMBOD(200),TROR(200),MA(4000),
1 FPD(4000),LDATA,NUMB,NUMR
COMMON/GEOM3/ EPS,IRHA(200)
COMMON/PAREM /XB(3),WB(3),F,IR,T,IDEF,F,PAREM
1 NHIST,WC,J12345,WP(3),XP(3),EPRIM,ATWT,PAREM
2 NCDB,CSTHT,U,LCHI,IATWT,IERR,IDBG,PAREM
3,IRPRIM,NASC,LSUPF,NBD,LRI,LRO,RIN,PAREM
4 ROUT,KLOOP,LOOP,ITYPE,PINF,NOA,DIST
COMMON/TAPE /INT,IOUT,IEOT,INT1,INT2,IAGG,ITERAN,ITERA
EQUIVALENCE (VHAB(1),V(1)),(VHAB(4),H(1)),(VHAB(7),A(1)),(VHAB(10)
1,B(1))
DATA IBOX/2,1,3/
L=LOCAT
LOOP=MA(L&1)
K=MA(L&6)
IF( LOOP.NE.KLOOP ) GO TO 1000
LRI=MA(L&3)
LRO=MA(L&4)
RIN=FPD(K)
ROUT=FPD(K&1)
GO TO 2005
1000 RIN=PINF
ROUT=-PINF
IF( (ITYPE.LT.1).OR.(ITYPE.GT.9) ) GO TO 2011
MA(L&1)=KLOOP
GO TO (1100,1200,1400,1300,1400,1600,1700,1800,1700 ),ITYPE
ARB SPH RCC REC TRC ELL BOX WED RPP
C
C
C ARB ARBITRARY POLYHEDRON
C
1100 DMIN=FPD(K&27)*1.0E-6
NSIDE= FPD(K&26)
I1=K&2
I2=I1& 4*NSIDE -1
L=0
DO 1190 I=I1,I2,4
DX= FPD(I)*XB(1) & FPD(I&1)*XB(2) & FPD(I&2)*XB(3) & FPD(I&3)
L=L&1
DY= -FPD(I)*WB(1) -FPD(I&1)*WB(2)-FPD(I&2)*WB(3)
IF( ABS(DY).LE.1.0E-6 ) GO TO 1190
DZ=DX/DY
PV(1)= XB(1) & DZ*WB(1)
PV(2)= XB(2) & DZ*WB(2)
PV(3)= XB(3) & DZ*WB(3)
GO 1120 J=I1,I2,4
IF( J.EQ.1) GO TO 1120
DX=FPD(J)*PV(1)&FPD(J&1)*PV(2)&FPD(J&2)*PV(3) & FPD(J&3)
IF( DX.GE.0. ) GO TO 1120
IF( -DX.LT.DMIN ) GO TO 1120
GO TO 1190
0 CONTINUE
IF( J.GT.ROUT) GO TO 1140

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16/71

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MEMBER NAME GG
RIN=DZ
LRI=L
GO TO 2000
1140 RIN=ROUT
LRI=LRO
LRO=L
ROUT=DZ
IF(RIN.GT.-PINF) GO TO 2000
1190 CONTINUE
GO TO 2000

C
C
1200 CONTINUE
DX= XB(1) -FPD(K&2)
DY= XB(2) -FPD(K&3)
DZ= XB(3) -FPD(K&4)
Y= DX*WB(1) & DY*WB(2) & DZ*WB(3)
C= DX*DX & DY*DY & DZ*DZ -FPD(K&5)**2
DX=Y*Y- C
IF( DX.LT.0.) GO TO 2000
DY=SQRT(DX)
RIN= -Y-DY
ROUT=-Y&DY
LRI=1
LRO=1
GO TO 2000

C
1300 DO 1301 I=1,12
J=K&1&I
1301 VHAB(I)=FPD(J)
RIN=-PINF
ROUT=PINF
LRO=0
LPI=0

C
C4 COMPUTE DOT PRODUCTS OF A.A AND B.B
C
AA=A(1)*A(1)&A(2)*A(2)&A(3)*A(3)
BB=B(1)*B(1)&B(2)*B(2)&B(3)*B(3)

C
C5 COMPUTE (V-XB) FOR X,Y,Z COORDINATES
C
V1XB1=V(1)-XB(1)
V2XB2=V(2)-XB(2)
V3XB3=V(3)-XB(3)

C
C6 TRANSFORM XV(X,Y,Z) TO THE COORDINATES OF THE REC
C
VPA=V1XB1*A(1)&V2XB2*A(2)&V3XB3*A(3)
VPR=V1XB1*B(1)&V2XB2*B(2)&V3XB3*B(3)

C
C7 TRANSFORM WB(X,Y,Z) TO THE COORDINATES OF THE REC
C
WBA=WB(1)*A(1)&WB(2)*A(2)&WB(3)*A(3)
WBB=WB(1)*B(1)&WB(2)*B(2)&WB(3)*B(3)
WBAWBA=WBA*WBA
WBBWBB=WBB*WBB
AAAA=AA*AA

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MEMBER NAME GG
      BBB=BB*BB
      AMBD=WBA*VPA*BBBB&WBB*VPB*AAAA
      UM=BBBB*VPA*VPA&AAAA*VPB*VPB-AAAA*BBBB
      DEN=WBAWBA*BBBB&WBBWBB*AAAA
      IF(ABS(DEN).LE.1.0E-6)GOTO 10
      AMBDA=AMBD/DEN
      UMU=UM/DEN
      DISC=AMBDA**2-UMU
      IF(DISC.LE.0.)GOTO 300

03  COMPUTE THE INTERSECT POINTS ON THE QUADRATIC SURFACE

      SD=SQRT(DISC)
      R1=AMBDA-SD
      R2=AMBDA&SD
      GOTO 20
10  R1=-PINF
      R2=PINF
20  HH=H(1)*H(1)&H(2)*H(2)&H(3)*H(3)
      WH=W(1)*H(1)&W(2)*H(2)&W(3)*H(3)
      VPH=V1XB1*H(1)&V2XB2*H(2)&V3XB3*H(3)

09  DETERMINE IF RAY PARALLEL TO PLANAR SURFACES

      IF(MH)40,70,50
40  IF(VPH.GE.0.)GOTO 300

10  COMPUTE THE INTERSECT POINTS ON THE PLANAR SURFACES

      CP=VPH/WH
      CM=(VPH&HH)/WH
      LCP=1
      LCM=2
      GOTO 100
50  VPHHH=VPH&HH
      IF(VPHHH.LE.0.)GOTO 300
      CP=VPHHH/WH
      CM=VPH/WH
      LCM=1
      LCP=2
      GOTO 100
70  CP=PINF
      CM=-CP
100 IF(CM.GT.R1)GOTO 110

11  R IN FOR THE QUADRATIC SURFACE

      RIN=R1
      LRI=3
      GOTO 120

12  R IN FOR A PLANAR SURFACE

110 RIN=CM
      LRI=LCM
120 IF(CP.LE.R2)GOTO 130

13  R OUT FOR THE QUADRATIC SURFACE

```

MEMBER NAME GG

C

ROUT=R2
LRO=3
GOTO 200

C14 ROUT FOR A PLANAR SURFACE

C

130 ROUT=CP
LRO=LCP
200 IF(ROUT.LE.RIN)GOTO300
GOTO(210,210,220),LRO

C15 DETERMINE IF ROUT OF PLANAR SURFACE OCCURS WITHIN ELLIPTIC
CROSS-SECTION

C

210 F1=DEN*ROUT**2-2.*AMBD*ROUT&UM
IF(F1)250,250,300

C16 DETERMINE IF ROUT OF QUADRATIC OCCURS BETWEEN PLANAR SURFACES

C

220 F1=ROUT*WH-VPH
IF(F1)300,250,230
230 IF(F1.GT.HH)GOTO 300
250 GOTO(260,260,270),LRI

C17 DETERMINE IF RIN OF PLANE WITHIN ELLIPTIC CROSS SECTION

C

260 F1=DEN*RIN**2-2.*AMBD*RIN&UM
IF(F1.GT.0.0)GO TO 300
GO TO 2000

C18 DETERMINE IF RIN OF QUADRATIC SURFACE BETWEEN PLANAR SURFACES

C

270 F1=RIN*WH-VPH
IF(F1)300,2000,280
280 IF(F1.LE.HH)GOTO 2000

C19 RAY MISSES BODY

C

300 RIN=PINF
ROUT=-PINF
LPT=0
LRO=0
GO TO 2000

C

C

1400 RB=FPD(K&8)
RT=FPD(K&9)
IF(ITYPE.EQ.3)RT=RB
DX=FPD(K&2)-XB(1)
DY=FPD(K&3)-XB(2)
DZ=FPD(K&4)-XB(3)
H1=FPD(K&5)
H2=FPD(K&6)
H3=FPD(K&7)
INTSEC=0
INTR1=0
INTR2=0

MEMBER NAME GG

```
PVPV=DX**2 & DY**2 & DZ**2
VPW=DX*WB(1) & DY*WB(2) & DZ*WB(3)
WH=H1*WB(1) & H2*WB(2) & H3*WB(3)
VPH=H1*DX & H2*DY & H3*DZ
HH=H1**2 & H2**2 & H3**2
RTRB=RT-RB
PRR=RB-RTRB/HH*VPH
VPHH=VPH & HH
UM=HH*(PVPV-PRR**2) -VPH**2
AMBDA=HH*VPW -WH*(VPH-RTRB*PRR)
DEN=HH -WH**2*(1.0&RTRB**2/HH)
IF(ABS(DEN).GT.1.0E-6) GO TO 1420
IF(RTRB.EQ.0) GO TO 1470
R2=UM/(2.0*AMBDA)
F1=R2*WH-VPH
IF(F1.LT.0.0) GO TO 1470
IF((F1-HH).GT.0.0) GO TO 1470
INTSEC=INTSEC&1
IF(WH.LE.0.0) GO TO 1405
IF(RTRB) 1410,1410,1415
1405 IF(RTRB.LE.0.0) GO TO 1415
1410 LRD=3
ROUT=R2
GO TO 1480
1415 LRI=3
RIN=R2
INTSEC=INTSEC&1
GO TO 1472
1420 AMBDA=AMBDA/DEN
DISC=AMBDA**2 -UM/DEN
IF(DISC) 1498,1470,1422
1422 SD=SQRT(DISC)
R1=AMBDA-SD
R2=AMBDA&SD
F1=R2*WH-VPH
IF(F1.LT.0.0) GO TO 1424
IF((F1-HH).GT.0.0) GO TO 1424
INTR2=INTR2&1
1424 F1=F1*WH-VPH
IF(F1.LT.0.0) GO TO 1426
IF((F1-HH).GT.0.) GO TO 1426
INTR1=INTR1&1
GO TO 1430
1426 IF(INTR2.EQ.0) GO TO 1470
ROUT=R2
RIN=R2
LRD=3
LRI=3
INTSEC=INTSEC&1
GO TO 1470
1430 IF(INTR2.GT.0) GO TO 1432
ROUT=R1
RIN=R1
LRD=3
LRI=3
INTSEC=INTSEC&1
GO TO 1470
1432 IF(R1-R2) 1434,1498,1436
```


MEMBER NAME GG

1434 RIN=R1
ROUT=R2
LRO=3
LRI=3
GO TO 1496

1436 RIN=R2
ROUT=R1
LRO=3
LRI=3
GO TO 1496

1470 IF(WH)1472,1498,1480
1472 IF(VPH.GE.0.0)GO TO 1498

CP=VPH/WH
F1=CP**2-2.0*CP*VPW & PVPV-RB**2
IF(F1.GT.0.0)GO TO 1474
INTSEC=INTSEC&1
ROUT=CP
LRO=1
IF(INTSEC.GE.2)GO TO 1496

1474 CM=VPHHH/WH
F1=CM**2-2.0*((VPW&WH)*CM-VPH)&HH&PVPV-RT**2
IF(F1.GT.0.0)GO TO 1498
PIN=CM
LRI=2
GO TO 1496

1480 IF(VPHHH.LT.0.0)GO TO 1498
CP=VPHHH/WH
F1=CP**2-2.0*((VPW&WH)*CP-VPH)&HH&PVPV-RT**2
IF(F1.GT.0.0)GO TO 1486
INTSEC=INTSEC&1
ROUT=CP
LRO=2

1486 IF(INTSEC.GT.1)GO TO 1496
CM=VPH/WH
F1=CM**2-2.0*CM*VPW&PVPV-RB**2
IF(F1.GT.0.0)GO TO 1498
RIN=CM
LPI=1

1496 GO TO 2000
1498 RIN=0.0
ROUT=-PINF
GO TO 2000

C

1600 CONTINUE
A1=0.
A2=0.
B1=0.
B2=0.
JA=K&1
DO 1610 J=1,3
JA=JA&1
DX=XB(J)-FPD(JA)
A1=A1&DX*WB(J)
B1=B1&DX*DX
DX=XB(J)-FPD(JA&3)
A2=A2&DX*WB(J)
1610 B2=B2&DX*DX
A1=2.0*A1

```

MEMBER NAME CG
A2=2.0*A2
C=FPD(K&8)
C2=2.0*C
X=(A2-A1)/C2
Y=( C**2&B2-B1)/C2
ALAMD=X*X-1.
ALAM1=( X*Y-A2*0.5)/ALAMD
U=(Y*Y-B2)/ALAMD
C=ALAM1*ALAM1-U
IF(C.LT.0 ) GO TO 2000
C=SQRT(C)
RIN= -ALAM1-C
ROUT=-ALAM1&C
LR1=1
LR0=1
GO TO 2000
1700 CONTINUE
RIN =-PINF
ROUT=&PINF
DO 1758 J=1,3
IF(ITYPE.LT.9)GO TO 1705
JV=K&2*I&1
X =FPD(JV)-FPD(JV-1)
VP= FPD(JV-1)-XB(I)
W =WB(I)
GO TO 1711
1705 JV=K&1
X=0.
VP=0.
W=0.
JA=JV&3*I
DO 1710 J=1,3
JV=JV&1
JA=JA&1
DX=FPD(JA)
VP=VP&(FPD(JV) -XB(J))*DX
W=W&WB(J)*DX
1710 X=X&DX*DX
1711 IF( W ) 1720,1712,1740
1712 IF(-VP.LT.0) GO TO 1799
IF(-VP-X )1798,1798,1799
1720 DY=VP/W
LO=2*IBDX(I)-1
IF(DY.LE.0 ) GO TO 1799
DZ=(VP&X)/W
LI=LO&1
GO TO 1760
1740 DY=(VP&X)/W
LO=2*IBDX(I)
IF( DY.LE.0) GO TO 1799
DZ=VP/W
LI=LO-1
1760 IF(ROUT.LE.DY) GO TO 1780
ROUT=DY
LRC=LO
1780 IF( RIN.GE.DZ) GO TO 1798
RIN=DZ
LRI=LI

```

MEMBER NAME GG
1798 CONTINUE
GO TO 2000
1799 RIN=PINF
ROUT=-PINF
GO TO 2000

C
1800 RIN=-PINF
ROUT=PINF
CM=-PINF
CP=PINF
L=0
L1=0
KK=0
LRI=0
LRQ=C
DX= XB(1)- FPD(K&2)
DY= XB(2)- FPD(K&3)
DZ= XB(3)- FPD(K&4)
DO 1830 I=1,3
JV=K&2&3*I
ASQ(I)=FPD(JV)**2 & FPD(JV&1)**2 & FPD(JV&2)**2
PV(I)=DX*FPD(JV) & DY*FPD(JV&1) & DZ*FPD(JV&2)
G(I)=WB(1)*FPD(JV)&WB(2)*FPD(JV&1) & WB(3)*FPD(JV&2)
IF(I.EQ.3) GO TO 1801
IF(G(I)) 1810,1811,1860
1810 IF(-PV(I).GE.0) GO TO 1840
TEMP=-PV(I)/G(I)
IF(TEMP.GE.CP) GO TO 1830
CP=TEMP
L=1
IF(I.GT.1) GO TO 1850
LRQ=3
GO TO 1830
1850 LRQ=1
GO TO 1830
1860 IF(-PV(I).LE.0) GO TO 1830
TEMP=-PV(I)/G(I)
IF(TEMP.LE.CM) GO TO 1830
CM=TEMP
KK=I
LRI=3
IF(I.EQ.1) GO TO 1830
LPI=1
GO TO 1830
1811 IF(PV(I).LE.0.) GO TO 1881
IF(PV(I).GE.ASQ(I)) GO TO 1881
1830 L1=L1&I
1801 IF(G(3)) 1815,1821,1823
1815 TEMP=-PV(3)&ASQ(3)
IF(TEMP.GE.0.) GO TO 1818
TEMP=TEMP/G(3)
IF(TEMP.LE.CM) GO TO 1819
CM=TEMP
KK=3
LPI=6
1818 IF(-PV(3).GE.0.) GO TO 1840
1819 TEMP=-PV(3)/G(3)

```

MEMBER NAME GG
IF(TEMP.GE.CP) GO TO 1829
CP=TEMP
L=3
LRD=5
GO TO 1829
18 IF(PV(3).LE.0.) GO TO 1840
IF(PV(3)-ASQ(3)) 1829,1829,1840
1823 IF(-PV(3).LE.0.) GO TO 1826
TEMP=-PV(3)/G(3)
IF(TEMP.LE.CM) GO TO 1826
CM=TEMP
KK=3
LRI=5
1826 TEMP=-PV(3)&ASQ(3)
IF(TEMP.LE.0) GO TO 1840
TEMP=TEMP/G(3)
IF(TEMP.GE.CP) GO TO 1829
CP=TEMP
L=3
LRD=6
1829 AG=ASQ(2)*G(1) & ASQ(1)*G(2)
PV4=PV(1)*ASQ(2) & PV(2)*ASQ(1)
TOP=ASQ(1)*ASQ(2)-PV4
IF(AG) 1831,1835,1833
1831 TEMP=TOP/AG
IF(TEMP.LE.CM) GO TO 1838
CM=TEMP
KK=4
LRI=2
GO TO 1838
1833 IF(TOP.LT.0.) GO TO 1840
TEMP=TOP/AG
IF(TEMP-CP) 1837,1838,1838
1835 IF(PV4.LE.0.) GO TO 1840
IF(-TOP) 1838,1840,1840
1837 CP=TEMP
L=4
LRD=2
1838 IF(L&KK.LE.0) GO TO 1840
ROUT=CP
RIN=CM
1840 CONTINUE
IF(ROUT.LT.PINF).AND.(ROUT.GT.0.).AND.(ROUT.GT.RIN)) GO TO 2000
1881 ROUT=-PINF
RIN=PINF
LRI=0
LRD=0
GO TO 2000
2000 MA(LOCAT&3)=LRI
MA(LOCAT&4)=LRD
IF(ROUT.LT.RIN) ROUT=-PINF
IF(ROUT.EQ.RIN) ROUT=ROUT*(1.&FPS*10.0)
FPD(K)=RIN
FPD(K&1)=ROUT
2005 RETURN
20 FORMAT(13H IN GG ITYPE=,I5,5X,3HIR=,I5,5X,4HMBO=,I5)
2011 WRITE(6,2010)ITYPE,IR,NBO

```

C1/73
C1/73
C1/73

01/73

← for $r_i = r_{out}$,
bump r_{out} by $(1 + \frac{10E}{...})$

F

6/71
6/71

MEMBER NAME GG
STOP
END

MEMBER NAME GGTEC

SUBROUTINE GGTEC(LOCAT)

(-----TREAT TEC BODY.

COMMON / GEOM2 / LOCREG(200),NUMBOD(200),IROR(200),MA(4000),

1 FPD(4000),LDATA,NUMB,NUMR

COMMON/GEOM3/EPS,IRHA(200)

COMMON/PAREM /XB(3),WB(3),E,IR,T,IDEF,F,PAREM

1 NHIST,WC,J12345,WP(3),XP(3),EPRIM,ATWT,PAREM

2 NCDB,CSTHT,U,LCHI,IATWT,IERR,IDBG,PAREM

3,IRPRIM,NASC,LSURF,NBO,LRI,LRO,RIN,PAREM

4 ROUT,KLOOP,LOOP,ITYPE,PINF,NOA,DIST

EQUIVALENCE(WB(1),WB111),(WB(2),WB222),(WB(3),WB333),(K,LF)

EPT=10.0*EPS

L=LOCAT

LOOP=MA(L&1)

K=MA(L&6)

IF(LOOP.NE.KLOOP) GO TO 1000

LF1=MA(L&3)

LRO=MA(L&4)

RIN=FPD(K)

ROUT=FPD(K&1)

GO TO 2005

1000 RIN=PINF

ROUT=-PINF

MA(L&1)=KLOOP

D1=FPD(LF&2)-XB(1)

D2=FPD(LF&3)-XB(2)

D3=FPD(LF&4)-XB(3)

BDC4 =D1*FPD(LF&8) &D2*FPD(LF&9) &D3*FPD(LF&10)

DDA =D1*FPD(LF&11) &D2*FPD(LF&12) &D3*FPD(LF&13)

HDA=FPD(K&20)

BDC8=D1*FPD(K&17) &D2*FPD(K&18) &D3*FPD(K&19)

TAU=FPD(K&23)

WDA=WB111*FPD(K&11) & WB222*FPD(K&12) & WB333*FPD(K&13)

WDN=WB111*FPD(K&8) & WB222*FPD(K&9) & WB333*FPD(K&10)

WDK=WB111*FPD(K&17) & WB222*FPD(K&18) & WB333*FPD(K&19)

IF(WDN.GT.EPT.OR.WDN.LT.-EPT) GO TO 1310

GAMMA=-BDC4/FPD(K&21)

IF(GAMMA.LT.0.0.OR.GAMMA.GT.1.)GO TO 2000

R1=FPD(K&14)

R2=FPD(K&15)

R3=R1/FPD(K&16)

R4=R2/FPD(K&16)

TM2=(GAMMA*(R3-R1)&R1)**2

TMM2=(GAMMA*(R4-R2)&R2)**2

V=GAMMA*HDA&DDA

TT=GAMMA*FPD(K&22) &BDC8

A=TMM2*WDA**2&TM2*WDK**2

B=-(TMM2*WDA*V&TM2*WDK*TT)

DISC=B**2-A*(TMM2*V**2&TM2*TT**2-TM2*TMM2)

IF(DISC) 2000,1306,1305

1305 DISC=SQRT(DISC)

1306 RIN=(-B-DISC)/A

ROUT=(-B&DISC)/A

LRI=3

LRO=3

GO TO 2000

1 0 FLIPD=1.0

IF(WDN.LT.0.0) GO TO 1315

DDN

DDA

DDK

```

MEMBER NAME GGTEC
FLTPD=-1.0
WDA=-WDA
WDN=-WDN
WDK=-WDK
1315 ALPHA=FPD(K&21)/WDN
BETA=BOC4/WDN
A=(ALPHA*WDA-HDA)**2&TAU*(ALPHA*WDK-FPD(K&22))**2 - FPD(K&24)
D=1.0/FPD(LF&16) - 1.0
BOC12 =-BOC8 *FPD(K&22)&D*FPD(LF&15)**2
B=-ALPHA*BETA*WDA**2&WDA*(ALPHA*DDA&BETA*HDA)-DDA*HDA
1 &TAU*(-ALPHA*BETA*WDK**2&ALPHA*WDK*BOC8
2 &BETA*WDK*FPD(K&22)&BOC12)
CC=(DDA-BETA*WDA)**2&TAU*((BOC8 -BETA*WDK)**2-FPD(K&15)**2)
DISC=B**2-A*CC
IF(DISC) 2000,1330,1320
1320 DISC= SQRT(DISC)
1330 IF(A.LT.EPT.AND.A.GT.-EPT) GO TO 1339
IF(A) 1335,1339,1340
1335 SIGMA1=(B-DISC)/A
SIGMA2=(B&DISC)/A
GO TO 1345
1339 SIGMA1=CC/(B&B)
SIGMA2=-PINF
IF(SIGMA1) 2000,1345,1345
1340 SIGMA1=(B&DISC)/A
SIGMA2=(B-DISC)/A
1345 SIGMAP=1.0E20
IF(FPD(K&16).LT.1.00001) GO TO 1346
SIGMAP=FPD(K&16)/(FPD(K&16)-1.0)
1346 IF(SIGMAP.LT.SIGMA2) GO TO 2000
IF(SIGMAP.GT.SIGMA1) GO TO 1347
IF(SIGMA2.LE.0.0) GO TO 2000
IF(SIGMA2-1.0) 1380,1380,1370
1347 IF(SIGMA2.GT.1.0.OR.SIGMA1.LT.0.0) GO TO 2000
IF(SIGMA1.LT.1.0) GO TO 1348
IF(SIGMA2) 1370,1370,1375
1348 IF(SIGMA2.GT.0.)GO TO 1360
LRI=3
LRO=1
RIN=ALPHA*SIGMA1 & BETA
ROUT=BETA
GO TO 1390
1360 LRI=3
LRO=3
RIN= ALPHA*SIGMA1 & BETA
ROUT=ALPHA*SIGMA2 & BETA
GO TO 1390
1370 LRI=2
LRO=1
RIN=ALPHA & BETA
ROUT=BETA
GO TO 1390
1375 LRI=2
LRO=3
RIN= ALPHA & BETA
ROUT=ALPHA*SIGMA2 & BETA
GO TO 1390
1380 LRI=3

```

MEMBER NAME GGTEC

LRO=1

RIN=ALPHA*SIGMA2 & BETA

ROUT=BETA

1390 IF(FLIPD.GE.0.0) GO TO 2000

RTP=RIN

ITP=LRI

RIN=-ROUT

LRI=LRO

ROUT=-RTP

LRO=ITP

2000 MA(LOCAT&3)=LRI

MA(LOCAT&4)=LRO

IF(ROUT.LT.RIN)ROUT=-PINF

IF(ROUT.EQ.RIN)ROUT=ROUT*(1.&EPT)

FPD(K)=RIN

FPD(K&1)=ROUT

2005 RETURN

END


```

MEMBER NAME GNORM
SUBROUTINE GNORM
DIMENSION X(3),H(3),IBOX1(3),IBOX2(3)
COMMON/GEOM2/LJCREG(200),NUMBOD(200),TROR(200),MA(4000),
1 FPD(4000),LDATA,NUMB,NUMR
COMMON/NORMAL/UN(3)
COMMON/PAREM 7XB(3),WB(3),E,IR,T,IDEF,F,
1 NHIST,WC,J12345,WP(3),XP(3),EPRIM,ATWT,
2 NCDB,CSTHT,U,LCHI,IATWT,IERR,IDBG
3, IPRIM,MASC,LSURF,NBO,LR1,LRD,RIN,
4 ROUT,KLOOP,LOOP,ITYPE,PINF,NOA,DIST
COMMON/TAPE /INT,IOUT,IEDT,INT1,INT2,IAGG,ITRAN,INTER
DATA (IBOX1(I),I=1,3)/10,7,4/
DATA (IBOX2(I),I=1,3)/4,10,7/

C
LSUR=IABS(LSURF)
DO 25 I=1,3
25 XP(I)=XB(I)&DIST*WB(I)
MASC=T*MASC
K=MA(MASC)
ITYPE=MA(MASC-4)
ARB SPH RCC REC TRC ELL BOX WED RPP TEC
GO TO (1100,1200,1400,1300,1400,1600,1700,1500,1900,1800),ITYPE
99 FORMAT(31H ROUND-OFF ERROR IN NORMAL NBO=,I5,6HLSURF=,I5,3HXP=,
1 3E12.5)
999 WRITE(IOUT,99)NBO,LSURF,(XP(I),I=1,3)
STOP 1

C ARB
1100 I=K&1&4*(LSUR-1)
DO 1110 J=1,3
1110 UN(J)=FPD(I&J)
GO TO 2000

C SPH
1200 DO 1210 I=1,3
1210 UN(I)=(XP(I)-FPD(K&1&I))/FPD(K&5)
GO TO 2000

C-----REC.
1300 IF(LSUR.EQ.3)GO TO 1310
K=K&4
GO TO 1502
1310 K=K&1
AN=FPD(K&7)**2&FPD(K&8)**2&FPD(K&9)**2
XMU=SQRT(AN-(FPD(K&10)**2&FPD(K&11)**2&FPD(K&12)**2))
YMU=1./(FPD(K&4)**2&FPD(K&5)**2&FPD(K&6)**2)
R1=0.0
I=K&3
DO 1320 J=1,3
1320 R1=(XP(J)-FPD(K&J)) * FPD(I&J)*YMU&R1
J=I&3
DO 1330 JJ=1,3
X(JJ)=FPD(K&JJ)&R1*FPD(I&JJ)
1330 H(JJ)=FPD(J&JJ)*XMU
DO 1340 JJ=1,3
UN(JJ)=X(JJ)&H(JJ)
1340 H(JJ)=X(JJ)-H(JJ)
DO 1350 JJ=1,3
1350 X(JJ)=XP(JJ)-UN(JJ)
AN=2.0*SQRT(AN/(X(1)**2&X(2)**2&X(3)**2))
DO 1360 JJ=1,3

```

MEMBER NAME GNDRM

1360 UN(JJ) = H(JJ) - UN(JJ) - AN*X(JJ)
GO TO 1505

C TRC AND RCC

1400 H2=0.0	NORM 360
DO 1410 I=1,3	NORM 370
H(I)=FPD(K&4&I)	NORM 380
1410 H2=H2&H(I)**2	NORM 390
GO TO (1415,1415,1435), LSUR	NORM 400
1415 H2=SQRT(H2)	NORM 410
DO 1420 I=1,3	NORM 420
1420 UN(I)=H(I)/H2	NORM 430
GO TO 2000	NORM 440
1435 DO 1440 I=1,3	NORM 450
1440 X(I)=XP(I)-FPD(K&1&I)	NORM 460
XMU=0.0	NORM 470
A2=0.0	NORM 480
DO 1445 I=1,3	NORM 490
J=MOD(I,3)&1	NORM 500
A2=A2&(H(I)*X(J)-H(J)*X(I))**2	NORM 510
1445 XMU=XMU&FPD(K&4&I)*X(I)	NORM 520
R=FPD(K&8)-FPD(K&9)	NORM 530
IF(ITYPE.FQ.3) R=0.0	NORM 540
B1=R/SQRT(H2*(H2&R**2))	NORM 550
B2=1.0/SQRT(A2*(H2&R**2))	NORM 560
DO 1450 I=1,3	NORM 570
1450 UN(I)=B2*(X(I)*H2-H(I)*XMU)&B1*H(I)	NORM 580
GO TO 2000	NORM 590

C---- WED (= RAW).

1500 IF(LSUR.EQ.2)GO TO 1550
IF(LSUR.EQ.3)K=K&4
IF(LSUR.EQ.1)K=K&7
IF(LSUR.GT.4)K=K&10
1502 DO 1503 J=1,3
1503 UN(J)=FPD(K&J)
1505 AN=1./SQRT(UN(1)**2&UN(2)**2&UN(3)**2)
DO 1510 J=1,3
1510 UN(J)=AN*UN(J)
GO TO 2000
1550 K=K&4
I=K&3
XMU= FPD(K&1)**2&FPD(K&2)**2&FPD(K&3)**2
AN= FPD(I&1)**2&FPD(I&2)**2&FPD(I&3)**2
DO 1560 J=1,3
1560 UN(J)=XMU*FPD(I&J)& AN*FPD(K&J)
GO TO 1505

C ELL

1600 DX=0.0	NORM 630
AN=0.0	NORM 640
C2=FPD(K&8)**2/4.0	NORM 650
DO 1620 I=1,3	NORM 660
IA=I&K&1	NORM 670
X(I)=XP(I)-.5*(FPD(IA)&FPD(IA&3))	NORM 680
H(I)=.5*(FPD(IA&3)-FPD(IA))	NORM 690
1620 DX=DX&X(I)*H(I)	NORM 700
DO 1630 I=1,3	NORM 710
UN(I)=C2*X(I)-DX*H(I)	NORM 720
1630 AN=AN&UN(I)**2	NORM 730
IF(AN.LT.1.0E-12) GO TO 999	NORM 740

MEMBER NAME GNORM

NORM 750
NORM 760
NORM 770
NORM 780

NORM 830
NORM 840
NORM 850
NORM 860
NORM 870
NORM 880
NORM 890
NORM 900
NORM 910
NORM 920
NORM 930
NORM 940
NORM 950
NORM 960
NORM 970
NORM 980
NORM 990

AN=SQRT(AN)
DO 1635 I=1,3
1635 UN(I)=UN(I)/AN
GO TO 2000

C JOX

1700 L= 1&(LSUR-I)/2
I1=IBOX1(L)
I2=IBOX2(L)
DO 1720 I=1,3
X(I)=FPD(K&I1&I)
1720 H(I)=FPD(K&I2&I)
AN=0.0
DO 1730 I=1,3
J=MOD(I,3)&1
JJ=MOD(I&1,3)&1
UN(I)=X(J)*H(JJ)-X(JJ)*H(J)
1730 AN=AN&UN(I)**2
IF(AN.LT.1.0E-12) GO TO 999
AN=SQRT(AN)
DO 1735 I=1,3
1735 UN(I)=UN(I)/AN
GO TO 2000

C-----TEC.

1800 IF(LSUR.EQ.3)GO TO 1820
K=K&7
DO 1810 J=1,3
1810 UN(J)=FPD(K&J)
GO TO 2000
1820 LF=K&2
XDN=XP(1)*FPD(LF&6)&XP(2)*FPD(LF&7)&XP(3)*FPD(LF&8)
HDN=1.0/FPD(K&21)
DDN=XDN-FPD(K&25)
A1=-DDN*HDN
R1=XP(1)-FPD(LF) &A1*FPD(LF&3)
R2=XP(2)-FPD(LF&1)&A1*FPD(LF&4)
R3=XP(3)-FPD(LF&2)&A1*FPD(LF&5)
B1=(R1*FPD(LF&9)&R2*FPD(LF&10)&R3*FPD(LF&11))/FPD(K&23)
B2=R1*FPD(K&17)&R2*FPD(K&18)&R3*FPD(K&19)
B3=FPD(K&20)*HDN
B4=FPD(K&22)*HDN
A2=FPD(LF&13)*(1.0/FPD(LF&14) -1.0)
A3=(-A1*A2&FPD(LF&13))*A2*HDN
A1=- (B1*B3&B2*B4&A3)
I=K&16
LF=LF&5
K=LF&3
DO 1850 J=1,3
1850 UN(J)=A1*FPD(LF&J)&R1*FPD(K&J)&B2*FPD(I&J)
GO TO 1505

T2-T1
TEMP1
TEMP2
TEMP3
T3
T4
T5
T6
R4-R2
EM*P*HDN

C RPP

1900 DO 1905 I=1,3
1905 UN(I)=0.0
GO TO (1910,1910,1920,1920,1930,1930), LSUR
1910 UN(2)=1.0
GO TO 2000
1920 UN(1)=1.0
GO TO 2000
1930 UN(3)=1.0

NOR 1000
NOR 1010
NOR 1020
NOR 1030
NOR 1040
NOR 1050
NOR 1060
NOR 1070

```
MEMBER NAME GNORM  
C-----OUTWARD NORMAL.  
2000 AN=UN(1)*WB(1)&UN(2)*WB(2)&UN(3)*WB(3)  
      IF(AN.LE.0.0)GO TO 3000  
      DO 2010 J=1,3  
10 UN(J)=-UN(J)  
3000 RETURN  
      END
```

NDF 1160

MEMBER NAME GP
SUBROUTINE GP(K)
C-----NEW NAME FOR SUBROUTINE PR .

COMMON/FEB073/DATEX
COMMON / DBG / N,NUM,LOCAT,ISAVE,INEXT,IRP,INEX,SMIN
COMMON / GEOM2 / LOCREG(200),NUMBOD(200),IROR(200),MA(4000),
FPD(4000),LDATA,NUMB,NUMR

1 COMMON/PAREM /XB(3),WB(3),E,IR,T,IDET,F,PAREM
1 NHIST,WC,J12345,WP(3),XP(3),EPRIM,ATWT,PAREM
2 NCDB,CSTHT,U,LCHI,IATWT,IERR,ICBG,PAREM
3, IRPRIM,NASC,LSURF,NBO,LRI,LRO,RIN,PAREM
4 RJUT,KLOOP,LOOP,ITYPE,PINF,NOA,DIST P31

IF(IDBG.EQ.1.AND.K.NE.8) GO TO 200

WRITE(6,50) K,XB,WB,IR

50 FORMAT(3H GP, I5,6E15.8,I5)

WRITE(6,100) IR,IRPRIM,NASC,LSURF,NBO,LRI,LRO,KLOOP,LOOP,ITYPE,
N,NUM,LOCAT,ISAVE,INEXT,IRP,INEX,LDATA,K,K, A

1 RIN,ROUT,SMIN,DIST

100 FORMAT(10I10,/10I10,/5E15.8)

200 RETURN

END

```

MEMBER NAME G1
SUBROUTINE G1(S)
COMMON/JAN243 / DATEX
LOGICAL LOGG
COMMON / DBG / N,NUM,LOCAT,ISAVE,INEXT,IRP,INEX,SMIN
COMMON / GEOM2 / LOCREG(200),NUMBOD(200),IROR(200),MA(4000),
1 FPD(4000),LDATA,NUMB,NUMR
COMMON/GEOM3/EPS,IRHA(200)
COMMON/PAREM /XB(3) ,WB(3) ,E ,IRTRU ,T ,IDET ,F , PAREM
-----
IR --- (NORMALLY).
1 NHIST ,WC ,J12345 ,WP(3) ,XP(3) ,EPRIM ,ATWT , PAREM
2 NCDB ,CSTHT ,U ,LCHI ,IATWT ,IERR ,IDBG , PAREM
3 , IRPRIM ,NASC ,LSURF ,NBO ,LRI ,LFO ,RIN , PAREM
4 ROUT ,KLOOP ,LOOP ,ITYPE ,PINF ,NOA ,DIST
COMMON/TAPE /INT ,IOUT ,IEDT ,INT1 ,INT2 ,IAGG ,ITRAN ,INTER ,TAPE
DATA LMAX/4000/,KLS/0/
SP=0.
IF(NASC.GT.0) GO TO 40
<LOOP=KLOOP&1
DIST=C.
40 IF(KLOOP.EQ.KLS)GO TO 110
IRH=IRHA(IRTRU)
IPL=1
IF(IRTRU.GT.1)IRL=IRHA(IRTRU-1)&1
IR=IRL
IF(IR.EQ.IRH)GO TO 110
DIS=(1.0-EPS)*DIST
DO 70 IRP=IRL,IRH
N=LOCREG(IRP)&1
NUM=NUMBOD(IRP)*4&N-4
DO 65 I=N,NUM,4
NBO=MA(I)
LOCAT=MA(I&1)
ITYPE=MA(LOCAT&2)
IF(ITYPE.NE.10)CALL GG(LOCAT)
IF(ITYPE.EQ.10)CALL GGTEC(LOCAT)
LOGG=(ROUT.LE.DIS ).OR.(RIN.GT.DIS )
IF(NBO)62,65,63
62 LOGG=.NOT.LOGG
63 IF(LOGG)GO TO 70
65 CONTINUE
IR=IRP
GO TO 110
70 CONTINUE
WRITE(IOUT,80)IRL,IRH,XB,WB,DIST
80 FORMAT(40H1REGION NOT FOUND FOR IRL,IRH/XB,WB,DIST,2I5/7E15.6)
STOP
110 SMIN=PINF
N=LOCREG(IR)&1
NUM=NUMBOD(IR)*4 &N-4
IF(IDBG.NE.0) CALL GP(1)
C THE LOOP UPTO 300 FINDS THE NEXT BODY THAT THE RAY WILL INTERSECT
C
ISAVE=0
DO 300 I=N,NUM,4
NBO=MA(I)
LOCAT=MA(I&1)
ITYPE=MA(LOCAT&2)
IF(ITYPE.NE.10)CALL GG(LOCAT)

```

```

MEMBER NAME G1
IF(ITYPE.EQ.10)CALL GGTEC(LOCAT)
IF(IDRG.NE.0) CALL GP(2)
IF(ROUT.LE.0) GO TO 300
IF( NBO ) 150,300,200
150 IF( (DIST.GT.RIN).OR.(RIN.GT.SMIN)) GO TO 300
SMIN=RIN
NASC=-NBO
LSURF=LRI
ISAVE=I
GO TO 300
200 IF( (DIST.GT.ROUT).OR.(ROUT.GT.SMIN))GO TO 300
SMIN=ROUT
NASC=NBO
LSURF=-LRO
ISAVE=I
300 CONTINUE
IF(ISAVE.NE.0) GO TO 309
WRITE(IOUT,305) IR,NHIST,J12345,NASC,N,NUM,NBO,LOCAT,LSURF,ISAVE,
1 LRO,ROUT,RIN,DIST,SMIN,E,XB,WB
305 FORMAT(24H NO VALID DISTANCE IN G1,/,1115,5E13.5,/,6E13.5)
IRPRIM=0
GO TO 5000

```

01/73

```

C
C NOW TO FIND NEXT REGION
C

```

```

309 S=SMIN -DIST&SP
DIST=SMIN
DIS=(1.0&EPS)*DIST
INEXT=ISAVE&2
310 IRP=MA(INEXT)
IF(IDBG.NE.0) CALL GP(3)
IF( IRP.EQ.0)GO TO 600
N=LOCREG(IRP)&1
NUM=NUMBOD(IRP)*4 & N-4

```

```

C
C THE LOOP TO 400 EXAMINES REGION IRP TO SEE IF IT IS THE NEXT REGION
C

```

```

IF(IDBG.NE.0) CALL GP(4)
DO 400 I=N,NUM,4
NBO=MA(I)
LOCAT=MA(I&1)
ITYPE=MA(LOCAT&2)
IF(ITYPE.NE.10)CALL GG(LOCAT)
IF(ITYPE.EQ.10)CALL GGTEC(LOCAT)
IF(IDBG.NE.0) CALL GP(5)
IF(NBO) 320,400 ,330
320 IF( (ROUT.LE.DIS ).OR.(RIN.GT.DIS ) ) GO TO 400
GO TO 500
330 IF( (RIN.LE.DIS ).AND.(DIS .LT.ROUT) ) GO TO 400
GO TO 500
400 CONTINUE

```

```

C
C FOUND A REGION
GO TO 750
500 INEX=INEXT & 1
INEXT=MA(INEX)
IF(INEXT.GT.0) GO TO 310

```

MEMBER NAME G1
C SEARCH ALL REGIONS
C

MA(INEX)=LDATA
INEXT=LDATA
LDATA=LDATA&2

1 J CONTINUE

IF(IDBG.NE.0) CALL GP(6)

DO 700 IRP=1,NUMR

IF(IRP.EQ.IR)GO TO 700

N=LOCREG(IRP)&1

NUM=NUMBDD(IRP)*4&N-4

DO 650 I=N,NUM,4

NBD=MA(I)

LOCAT=MA(I&1)

ITYPE=MA(LOCAT&2)

IF(ITYPE.NE.10)CALL GG(LOCAT)

IF(ITYPE.EQ.10)CALL GGTEC(LOCAT)

IF(IDBG.NE.0) CALL GP(7)

IF(NBD) 620,650,630

620 IF((ROUT.LE.DIS).OR.(RIN.GT.DIS)) GO TO 650

GO TO 700

630 IF((RIN.LE.DIS).AND.(DIS .LT.ROUT)) GO TO 650

GO TO 700

650 CONTINUE

MA(INEXT)=IRP

IF(INEXT.LT.LMAX) GO TO 750

WRITE(IOUT,655) NHIST,KLOOP

655 FORMAT(21H GEOMETRY ARRAY FULL ,2110)

IRPRIM=0

GO TO 5000

7 J CONTINUE

WRITE(IOUT,703)IRTRU,IR,XB,WB,DIST

703 FORMAT(22HONEXT REGION NOT FOUND/7H IRTRU=I5,4X,

C 4H IR=I5,5X,3HXB=3E15.6/4H WB=3E15.6,5X,5HDIST=E15.6)

IRPRIM=0

5000 KLS=KLOOP

RETURN

750 IRPRIM=IRDR(IRP)

IF(!DBG.NE.0) CALL GP(8)

IR=IRP

IF(IRPRIM.NE.IRTRU)GO TO 5000

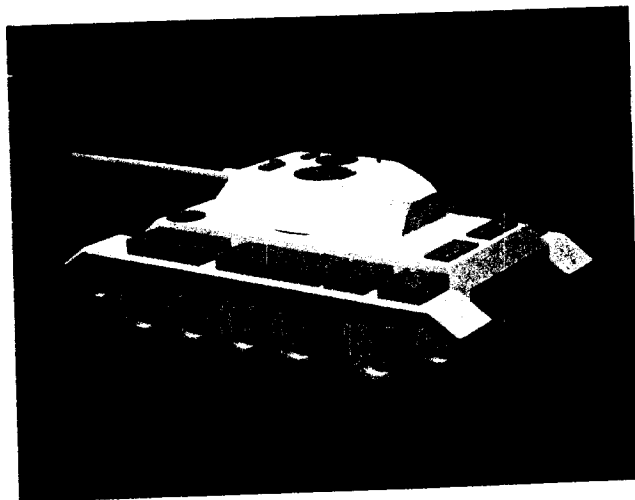
SP=SP&S

GO TO 110

END

APPENDIX B

CG T-54 TANK INPUT (LISTING)



Picture generated by
MAGI SynthaVision process

			TANK			
ARB	1	0				
		13.	5.	-3.5	19.	4.2
		1.	4.2	-3.5	2.	5.
		18.	5.	3.5	19.	4.2
		1.	4.2	3.5	2.	5.
		1234.	5678.	1562.	2673.	3784.
ARB	2	19.	4.2	-3.5	20.8	2.5
		1.	2.5	-3.5	1.	4.2
		19.	4.2	3.5	20.8	2.5
		1.	2.5	3.5	1.	4.2
		1234.	5678.	1562.	2673.	3784.
ARB	3	20.8	2.5	-3.5	18.	1.
		1.2	1.	-3.5	1.	2.5
		20.8	2.5	3.5	18.	1.
		1.2	1.	3.5	1.	2.5
		1234.	5678.	1562.	2673.	3784.
ARB	4	20.5	4.	-6.	22.	3.
		21.8	3.	-6.	20.5	3.8
		20.5	4.	-3.5	22.	3.
		21.8	3.	-3.5	20.5	3.8
		1234.	5678.	1562.	2673.	3784.
ARB	5	1.5	3.8	-6.	19.	0.
		0.	0.2	0.	0.	0.
ARB	6	1.5	4.	-6.	1.5	3.8
		0.2	3.	-6.	0.	3.
		1.5	4.	-3.5	1.5	3.8
		0.2	3.	-3.5	0.	3.
		1234.	5678.	1562.	2673.	3784.
ARB	7	20.5	4.	6.	22.	3.
		21.8	3.	6.	20.5	3.8
		20.5	4.	3.5	22.	3.
		21.8	3.	3.5	20.5	3.8
		1234.	5678.	1562.	2673.	3784.
ARB	8	1.5	3.8	3.5	19.	0.
		0.	0.2	0.	0.	0.
ARB	9	1.5	4.	6.	1.5	3.8
		0.2	3.	6.	0.	3.
		1.5	4.	3.5	1.5	3.8
		0.2	3.	3.5	0.	3.
		1234.	5678.	1562.	2673.	3784.
ARB	10	20.2	2.3	-5.5	0.	0.
		0.9				
ARB	11	20.2	2.3	-5.6	0.	0.
		0.75				
ARB	12	20.2	2.3	-5.3	0.	0.
		0.2				
ARB	13	17.5	1.5	-5.5	0.	0.
		1.3				
ARB	14	17.5	1.5	-5.6	0.	0.
		1.1				
ARB	15	17.5	1.5	-5.3	0.	0.
		0.2				
ARB	16	14.5	1.5	-5.5	0.	0.
		1.3				
ARB	17	14.5	1.5	-5.6	0.	0.
		1.1				
ARB		14.5	1.5	-5.3	0.	0.
		0.2				

RCC 19	11.5	1.5	-5.5	0.	0.	1.7
	1.3					
RCC 20	11.5	1.5	-5.6	0.	0.	0.5
	1.1					
RCC 21	11.5	1.5	-5.3	0.	0.	0.3
	0.2					
RCC 22	8.5	1.5	-5.5	0.	0.	1.7
	1.3					
RCC 23	8.5	1.5	-5.6	0.	0.	0.5
	1.1					
RCC 24	8.5	1.5	-5.3	0.	0.	0.3
	0.2					
RCC 25	4.5	1.5	-5.5	0.	0.	1.7
	1.3					
RCC 26	4.5	1.5	-5.6	0.	0.	0.5
	1.1					
RCC 27	4.5	1.5	-5.3	0.	0.	0.3
	0.2					
RCC 28	1.5	2.3	-5.5	0.	0.	1.7
	0.9					
RCC 29	1.5	2.3	-5.6	0.	0.	0.5
	0.75					
RCC 30	1.5	2.3	-5.3	0.	0.	0.3
	0.2					
RCC 31	20.2	2.3	3.8	0.	0.	1.7
	0.9					
RCC 32	17.5	1.5	3.8	0.	0.	1.7
	1.3					
RCC 33	14.5	1.5	3.8	0.	0.	1.7
	1.3					
RCC 34	11.5	1.5	3.8	0.	0.	1.7
	1.3					
RCC 35	8.5	1.5	3.8	0.	0.	1.7
	1.3					
RCC 36	4.5	1.5	3.8	0.	0.	1.7
	1.3					
RCC 37	1.5	2.3	3.8	0.	0.	1.7
	0.9					
BOX 38	4.2	2.8	-6.	13.6	0.	0.
	0.	0.2	0.	0.	0.	2.5
ARB 39	17.8	3.	-6.	20.2	3.4	-6.
	20.2	3.2	-6.	17.8	2.8	-6.
	17.8	3.	-3.5	20.2	3.4	-3.5
	20.2	3.2	-3.5	17.8	2.8	-3.5
	1234.	5678.	1562.	2673.	3784.	1584.
ARB 40	20.3	3.4	-6.	20.8	3.25	-6.
	20.7	3.1	-6.	20.2	3.2	-6.
	20.3	3.4	-3.5	20.8	3.25	-3.5
	20.7	3.1	-3.5	20.2	3.2	-3.5
	1234.	5678.	1562.	2673.	3784.	1584.
ARB 41	20.8	3.25	-6.	21.3	2.6	-6.
	21.1	2.6	-6.	20.7	3.1	-6.
	20.8	3.25	-3.5	21.3	2.6	-3.5
	21.1	2.6	-3.5	20.7	3.1	-3.5
	1234.	5678.	1562.	2673.	3784.	1584.
BOX 42	21.1	2.	-6.	0.2	0.	0.
	0.	0.6	0.	0.	0.	2.5
ARB 43	21.1	2.	-6.	21.3	2.	-6.

	20.93	1.45	-6.	20.8	1.6	-6.
	21.1	2.	-3.5	21.3	2.	-3.5
	20.93	1.45	-3.5	20.8	1.6	-3.5
	1234.	5678.	1562.	2673.	3784.	1584.
ARB 44	20.8	1.6	-6.	20.93	1.45	-6.
	17.8	0.	-6.	17.8	0.2	-6.
	20.8	1.6	-3.5	20.93	1.45	-3.5
	17.8	0.	-3.5	17.8	0.2	-3.5
	1234.	5678.	1562.	2673.	3784.	1584.
BOX 45	4.2	0.	-6.	13.6	0.	0.
	0.	0.2	0.	0.	0.	2.5
ARB 46	4.2	0.	-6.	0.9	1.38	-6.
	1.	1.5	-6.	4.2	0.2	-6.
	4.2	0.	-3.5	0.9	1.38	-3.5
	1.	1.5	-3.5	4.2	0.2	-3.5
	1234.	5678.	1562.	2673.	3784.	1584.
ARB 47	C.9	1.38	-6.	1.	1.5	-6.
	C.6	2.	-6.	0.4	2.	-6.
	C.9	1.38	-3.5	1.	1.5	-3.5
	C.6	2.	-3.5	0.4	2.	-3.5
	1234.	5678.	1562.	2673.	3784.	1584.
BOX 48	C.4	2.	-6.	0.2	0.	0.
	0.	0.6	0.	0.	0.	2.5
ARB 49	C.4	2.6	-6.	0.6	2.6	-6.
	1.	3.1	-6.	0.9	3.28	-6.
	C.4	2.6	-3.5	0.6	2.6	-3.5
	1.	3.1	-3.5	0.9	3.28	-3.5
	1234.	5678.	1562.	2673.	3784.	1584.
ARB 50	C.9	3.28	-6.	1.	3.1	-6.
	1.5	3.2	-6.	1.5	3.4	-6.
	0.9	3.28	-3.5	1.	3.1	-3.5
	1.5	3.2	-3.5	1.5	3.4	-3.5
	1234.	5678.	1562.	2673.	3784.	1584.
ARB 51	1.5	3.2	-6.	1.5	3.4	-6.
	4.2	3.	-6.	4.2	2.8	-6.
	1.5	3.2	-3.5	1.5	3.4	-3.5
	4.2	3.	-3.5	4.2	2.8	-3.5
	1234.	5678.	1562.	2673.	3784.	1584.
BOX 52	4.2	2.8	3.5	13.6	0.	0.
	0.	0.2	0.	0.	0.	2.5
ARB 53	17.8	3.	6.	20.2	3.4	6.
	20.2	3.2	6.	17.8	2.8	6.
	17.8	3.	3.5	20.2	3.4	3.5
	20.2	3.2	3.5	17.8	2.8	3.5
	1234.	5678.	1562.	2673.	3784.	1584.
ARB 54	20.3	3.4	6.	20.8	3.25	6.
	20.7	3.1	6.	20.2	3.2	6.
	20.3	3.4	3.5	20.8	3.25	3.5
	20.7	3.1	3.5	20.2	3.2	3.5
	1234.	5678.	1562.	2673.	3784.	1584.
ARB 55	20.8	3.25	6.	21.3	2.6	6.
	21.1	2.6	6.	20.7	3.1	6.
	20.8	3.25	3.5	21.3	2.6	3.5
	21.1	2.6	3.5	20.7	3.1	3.5
	1234.	5678.	1562.	2673.	3784.	1584.
BOX 56	21.1	2.	3.5	0.2	0.	0.
	0.	0.6	0.	0.	0.	2.5
ARB 57	21.1	2.	6.	21.3	2.	6.

	20.93	1.45	6.	20.8	1.6	6.
	21.1	2.	3.5	21.3	2.	3.5
	20.93	1.45	3.5	20.8	1.6	3.5
	1234.	5678.	1562.	2673.	3784.	1584.
ARB 58	20.8	1.6	6.	20.93	1.45	6.
	17.8	0.	6.	17.8	0.2	6.
	20.8	1.6	3.5	20.93	1.45	3.5
	17.8	0.	3.5	17.8	0.2	3.5
	1234.	5678.	1562.	2673.	3784.	1584.
BOX 59	4.2	0.	3.5	13.6	0.	0.
	0.	0.2	0.	0.	0.	2.5
ARB 60	4.2	0.	6.	0.9	1.38	6.
	1.	1.5	6.	4.2	0.2	6.
	4.2	0.	3.5	0.9	1.38	3.5
	1.	1.5	3.5	4.2	0.2	3.5
	1234.	5678.	1562.	2673.	3784.	1584.
ARB 61	0.9	1.38	6.	1.	1.5	6.
	0.6	2.	6.	0.4	2.	6.
	0.9	1.38	3.5	1.	1.5	3.5
	0.6	2.	3.5	0.4	2.	3.5
	1234.	5678.	1562.	2673.	3784.	1584.
BOX 62	0.4	2.	3.5	0.2	0.	0.
	0.	0.6	0.	0.	0.	2.5
ARB 63	0.4	2.6	6.	0.6	2.6	6.
	1.	3.1	6.	0.9	3.28	6.
	0.4	2.6	3.5	0.6	2.6	3.5
	1.	3.1	3.5	0.9	3.28	3.5
	1234.	5678.	1562.	2673.	3784.	1584.
ARB 64	0.9	3.28	6.	1.	3.1	6.
	1.5	3.2	6.	1.5	3.4	6.
	0.9	3.28	3.5	1.	3.1	3.5
	1.5	3.2	3.5	1.5	3.4	3.5
	1234.	5678.	1562.	2673.	3784.	1584.
ARB 65	1.5	3.2	6.	1.5	3.4	6.
	4.2	3.	6.	4.2	2.8	6.
	1.5	3.2	3.5	1.5	3.4	3.5
	4.2	3.	3.5	4.2	2.8	3.5
	1234.	5678.	1562.	2673.	3784.	1584.
BOX 66	13.5	4.0	-5.8	4.3	0.	0.
	0.	0.7	0.	0.	0.	2.3
BOX 67	7.	4.	-5.8	5.5	0.	0.
	0.	0.7	0.	0.	0.	2.3
BOX 68	4.7	4.	-5.8	2.	0.	0.
	0.	0.7	0.	0.	0.	2.3
BOX 69	2.	4.	-5.8	2.	0.	0.
	0.	0.7	0.	0.	0.	2.3
BOX 70	14.8	4.	3.5	3.2	0.	0.
	0.	0.7	0.	0.	0.	2.3
BOX 71	11.	4.	4.8	2.	0.	0.
	0.	0.7	0.	0.	0.	1.
BOX 72	6.	4.	3.5	3.3	0.	0.
	0.	0.7	0.	0.	0.	2.3
BOX 73	2.2	4.	3.5	3.3	0.	0.
	0.	0.7	0.	0.	0.	2.3
BOX 74	19.	3.7	-3.3	0.2	0.	0.
	0.	0.6	0.	0.	0.	6.6
TEC 75	11.	5.4	0.	0.	2.1	0.
	0.	1.	0.	1.	0.	0.

	6.9	3.4	1.2			
BOX 76	3.9	5.3	-2.5	1.4	0.	0.
	0.	1.7	0.	0.	0.	0.
ARB 77	4.	6.4	-3.4	8.5	7.6	5.
	8.5	7.7	-3.4	4.	7.7	-3.4
	4.	6.4	3.4	8.5	7.6	-3.4
	8.5	7.7	3.4	4.	7.7	3.4
ARB 78	1234.	5678.	1562.	2673.	3784.	3.4
	13.9	7.6	-3.4	17.	7.6	1584.
	18.	5.3	-3.4	15.8	5.3	-3.4
	13.9	7.6	3.4	17.	7.6	-3.4
	18.	5.3	3.4	15.8	5.3	3.4
RCC 79	1234.	5678.	1562.	2673.	3784.	3.4
	11.	5.	0.	0.	1.	1584.
	2.5					0.
RCC 80	10.	7.4	-1.	0.	0.2	0.
	1.3					
RCC 81	11.	7.4	1.5	0.	0.2	0.
	1.					
RCC 82	17.	4.9	-2.5	0.	0.2	0.
	0.95					
RCC 83	14.	6.5	0.	2.5	0.	0.
	0.4					
RCC 84	16.5	6.5	0.	10.5	0.	0.
	0.2					
BOX 85	2.3	5.	-3.	1.2	0.	0.
	0.	0.2	0.	0.	0.	0.
BOX 86	2.3	5.	0.5	1.2	0.	2.5
	0.	0.2	0.	0.	0.	0.
BOX 87	8.6	7.5	-1.6	0.3	0.	2.5
	0.	0.15	0.	0.	0.	0.
B 88	12.5	7.5	-1.7	0.6	0.	1.2
	0.	0.2	0.	0.	0.	0.
BOX 89	12.3	7.5	1.	0.4	0.	1.3
	0.	0.2	0.	0.	0.	0.
RCC 90	13.4	7.5	0.	0.	0.	1.
	0.3					
RCC 91	9.	7.5	2.	0.	0.5	0.
	0.1					
RPP 92	-100000.	100000.	-100000.	100000.	-100000.	100000.
RPP 93	-1000100.	1000100.	-1000100.	1000100.	-1000100.	1000100.
RPP 94	-1.	28.	5.3	8.	-7.	7.
RPP 95	-1.	28.	-1.	5.4	-3.5	3.5
RPP 96	-1.	28.	3.5	5.4	-7.4	-3.4
RPP 97	-1.	28.	3.5	5.4	3.4	7.
RPP 98	19.	28.	-1.	3.6	-7.	-3.4
RPP 99	15.9	19.1	-1.	3.6	-7.	-3.4
RPP 100	6.9	16.	-1.	3.6	-7.	-3.4
RPP 101	2.7	7.	-1.	3.6	-7.	-3.4
RPP 102	-1.	2.8	-1.	3.6	-7.	-3.4
RPP 103	19.	28.	-1.	3.6	-7.	-3.4
RPP 104	6.9	19.1	-1.	3.6	3.4	7.
RPP 105	-1.	7.	-1.	3.6	3.4	7.
FND						
1	1	0	0	0		
2	2					
	3	0	0	0		
4	4	0	0	0		

5	5	0	0	0
6	6	0	0	0
7	7	0	0	0
8	8	0	0	0
9	9	0	0	0
10	10	-11	-12	0
11	12	0	0	0
12	13	-14	-15	0
13	15	0	0	0
14	16	-17	-18	0
15	18	0	0	0
16	19	-20	-21	0
17	21	0	0	0
18	22	-23	-24	0
19	24	0	0	0
20	25	-26	-27	0
21	27	0	0	0
22	28	-29	-30	0
23	30	0	0	0
24	31	0	0	0
25	32	0	0	0
26	33	0	0	0
27	34	0	0	0
28	35	0	0	0
29	36	0	0	0
30	37	0	0	0
31	38	0	0	0
32	39	0	0	0
33	40	0	0	0
34	41	0	0	0
35	42	0	0	0
36	43	0	0	0
37	44	0	0	0
38	45	0	0	0
39	46	0	0	0
40	47	0	0	0
41	48	0	0	0
42	49	0	0	0
43	50	0	0	0
44	51	0	0	0
45	52	0	0	0
46	53	0	0	0
47	54	0	0	0
48	55	0	0	0
49	56	0	0	0
50	57	0	0	0
51	58	0	0	0
52	59	0	0	0
53	60	0	0	0
54	61	0	0	0
55	62	0	0	0
56	63	0	0	0
57	64	0	0	0
58	65	0	0	0
59	65	0	0	0
60	67	0	0	0
61	68	0	0	0
62	69	0	0	0

63	70	0	0	0					
64	71	0	0	0					
65	72	0	0	0					
66	73	0	0	0					
67	74	0	0	0					
68	75	-76	-77	-78					
69	79	0	0	0					
70	80	0	0	0					
71	81	0	0	0					
72	82	0	0	0					
73	83	0	0	0					
74	84	0	0	0					
75	85	0	0	0					
76	86	0	0	0					
77	87	0	0	0					
78	88	0	0	0					
79	89	0	0	0					
80	90	0	0	0					
81	91	0	0	0					
82	11	-12							
83	14	-15							
84	17	-18							
85	20	-21							
86	23	-24							
87	26	-27							
88	29	-30							
89	76								
90	77								
91	78	-84	-83						
92	92	-94	-95	-96	-97	-98	-99	-100	-101
	-102	-103	-104	-105					
	93	-92							
94	94	-75	-79	-80	-81	-83	-84	-87	-88
	-89	-90	-91						
95	95	-1	-2	-3	-74	-79	-82	-85	-86
96	96	-1	-2	-4	-5	-6	-66	-67	-68
	-69	-82							
97	97	-1	-2	-7	-8	-9	-70	-71	-72
	-73								
98	98	-2	-3	-4	-10	-12	-39	-40	-41
	-42	-43	-44						
99	99	-2	-3	-13	-15	-38	-39	-44	-45
100	100	-2	-3	-16	-18	-19	-21	-22	-24
	-38	-45							
101	101	-2	-3	-25	-27	-45	-46	-51	-38
102	102	-2	-3	-6	-28	-30	-46	-47	-48
	-49	-50	-51						
103	103	-2	-3	-7	-31	-53	-54	-55	-56
	-57	-58							
104	104	-2	-3	-33	-34	-35	-52	-53	-58
	-59	-32							
105	105	-2	-3	-36	-37	-52	-59	-60	-61
	-62	-63	-64	-65	-9				
END									